

Integrated Circuits for Digital Communications

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Basic Baseband PAM Concepts

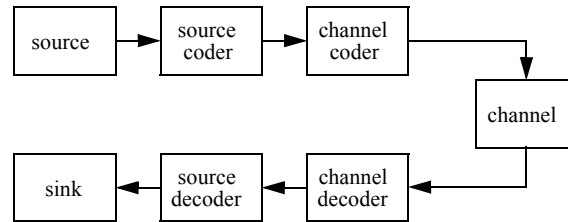


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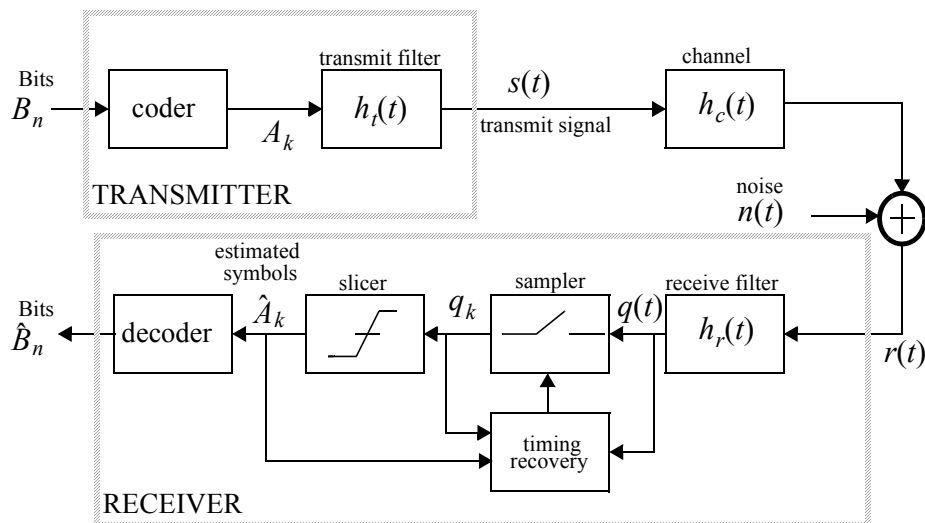
General Data Communication System



- Source coder removes redundancy from source (i.e. MPEG, ADPCM, text compression, etc.)
- Channel coder introduces redundancy to maximize information rate over channel. (i.e. error-correcting codes, trellis coding, etc.)
- Our interest is in channel coding/decoding and channel transmission/reception.



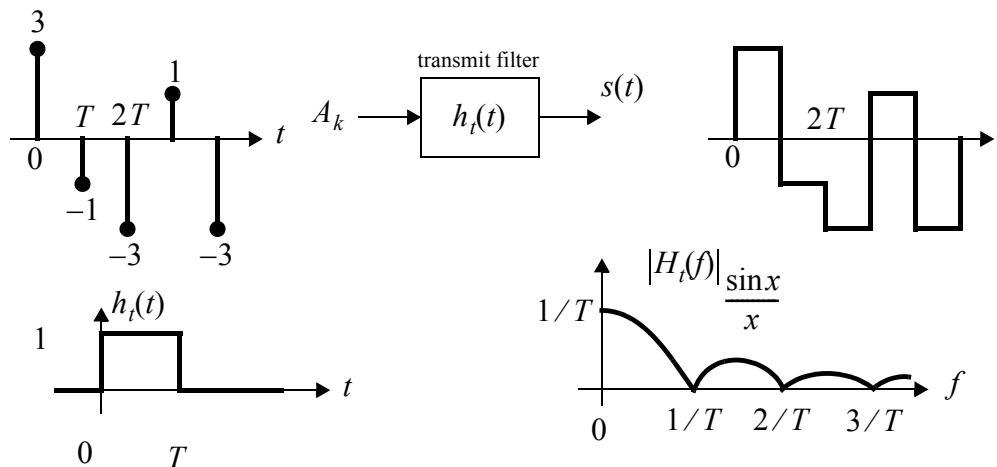
Basic Baseband System



- In 2B1Q, coder maps pairs of bits to one of four levels —
 $A_k = \{-3, -1, 1, 3\}$



Rectangular Transmit Filter



- The spectrum of A_k is flat if random.
- The spectrum of $s(t)$ is same shape as $H_t(f)$



Nyquist Pulses

- $h(t)$ is the impulse response for transmit filter, channel and receive filter (\otimes denotes convolution)

$$h(t) = h_t(t) \otimes h_c(t) \otimes h_r(t) \quad (1)$$

$$q(t) = \sum_{m=-\infty}^{\infty} A_m h(t-mT) + n(t) \otimes h_r(t) \quad (2)$$

- The received signal, $q(t)$, is sampled at kT .

$$q_k = \sum_{m=-\infty}^{\infty} A_m h(kT-mT) + u(kT) \quad , \quad u(t) \equiv n(t) \otimes h_r(t) \quad (3)$$

- For zero intersymbol interference (i.e. $q_k = A_k + u_k$)

$$h(kT) = \delta_k \quad (\delta_k = 0, 1, 0, 0, 0, \dots) \quad (4)$$



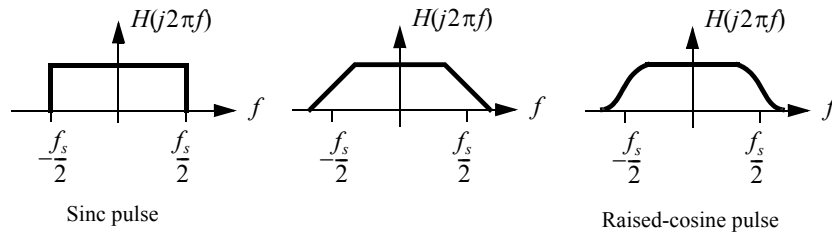
Nyquist Pulses

- For zero ISI, the same criteria in the frequency domain is:
($f_s = 1/T$)

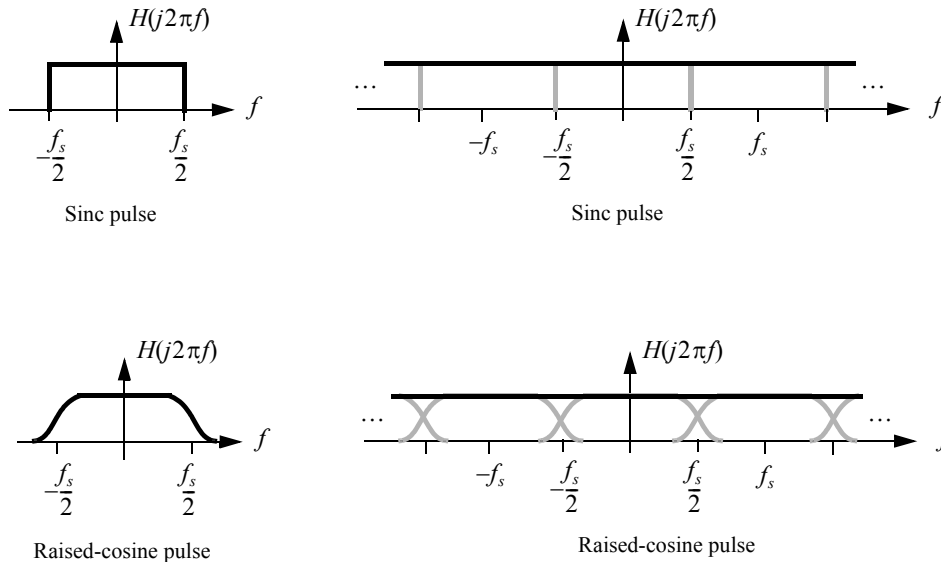
$$\frac{1}{T} \sum_{m=-\infty}^{\infty} H(j2\pi f + jm2\pi f_s) = 1 \quad (5)$$

- Known as Nyquist Criterion

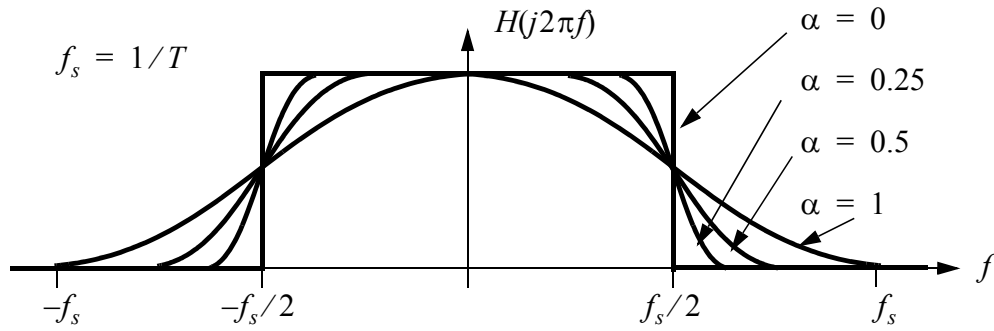
Example Nyquist Pulses (in freq domain)



Nyquist Pulses



Raised-Cosine Pulse

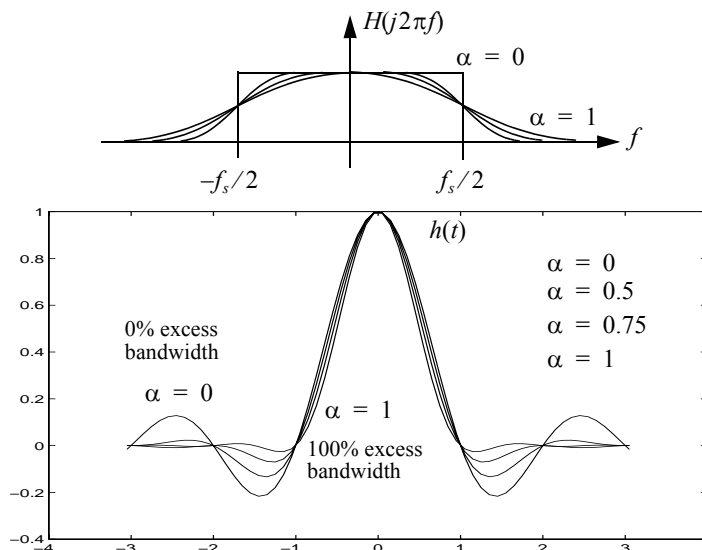


$$H(j2\pi f) = \begin{cases} T; & 0 \leq |f| \leq (1-\alpha)\left(\frac{f_s}{2}\right) \\ \frac{T}{2} \left[1 + \cos \left[\frac{\pi}{2\alpha} \left(\frac{|2f|}{f_s} - (1-\alpha) \right) \right] \right] & (1-\alpha)\left(\frac{f_s}{2}\right) \leq |f| \leq (1+\alpha)\left(\frac{f_s}{2}\right) \\ 0; & |f| > (1+\alpha)\left(\frac{f_s}{2}\right) \end{cases}$$

- α determines *excess bandwidth*



Raised-Cosine Pulses



- More excess bandwidth — impulse decays faster.



Raised-Cosine Pulse

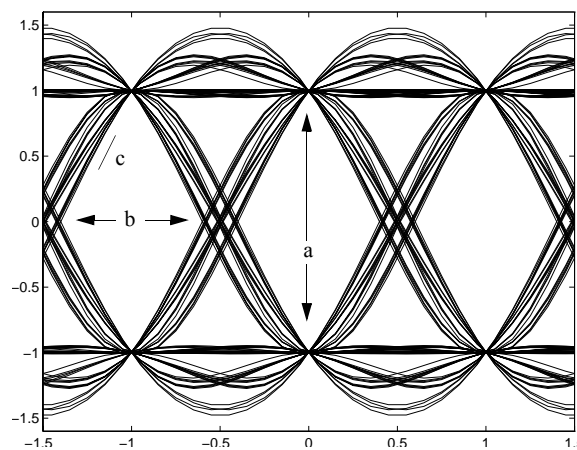
- α determines amount of excess bandwidth past $f_s/2$
- Example: $\alpha = 0.25$ implies that bandwidth is 25 percent higher than $f_s/2$ while $\alpha = 1$ implies bandwidth extends up to f_s .
- Larger excess bandwidth — easier receiver
- Less excess bandwidth — more efficient channel use

Example

- Max symbol-rate if a 50% excess bandwidth is used and bandwidth is limited to 10kHz
- $1.5 \times (f_s/2) = 10 \text{ kHz}$ implies $f_s = 13.333 \times 10^3 \text{ symbols/s}$



Eye Diagram

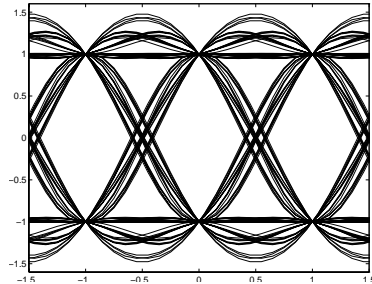


- “a” indicates immunity to noise
- “b” indicates immunity to errors in timing phase
- slope “c” indicates sensitivity to jitter in timing phase

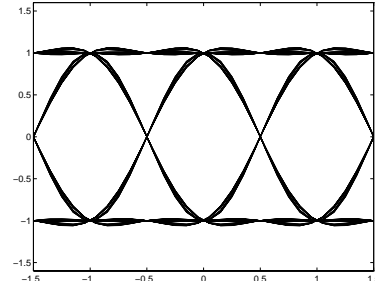


Eye Diagram

- Zero crossing — NOT a good performance indicator
- 100% bandwidth has little zero crossing jitter
- 50% BW has alot of zero crossing jitter but it is using less bandwidth



$\alpha = 0.5$ 50% excess bandwidth

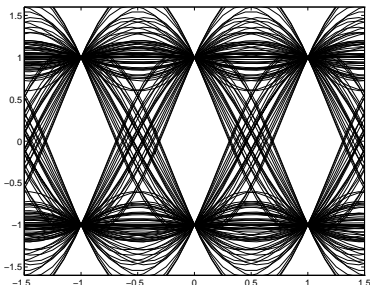


$\alpha = 1$ 100% excess bandwidth

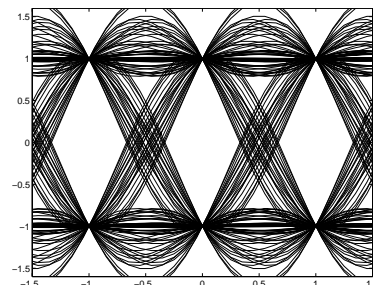
- Less excess BW — more intolerant to timing phase



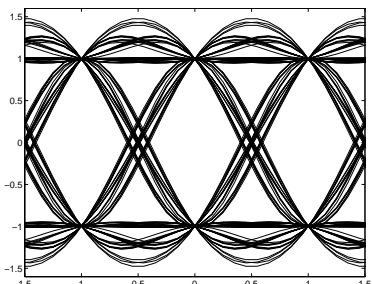
Example Eye Diagrams



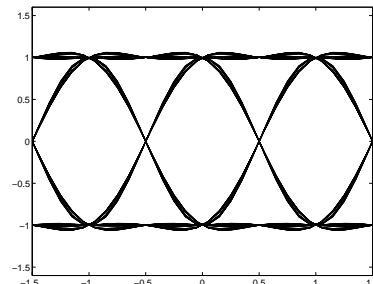
$\alpha = 0$ 0% excess bandwidth



$\alpha = 0.25$ 25% excess bandwidth



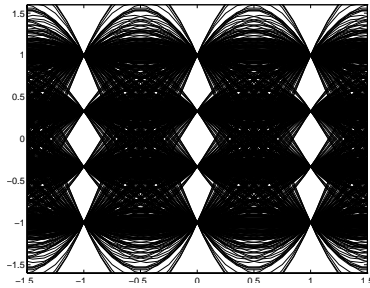
$\alpha = 0.5$ 50% excess bandwidth



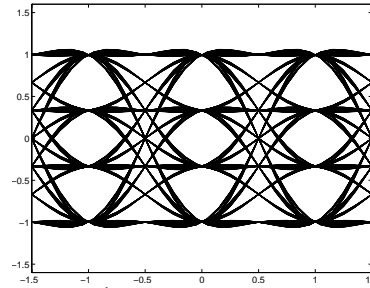
$\alpha = 1$ 100% excess bandwidth



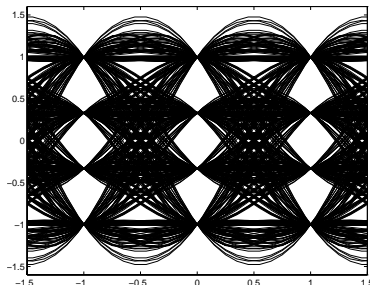
Example Eye Diagrams



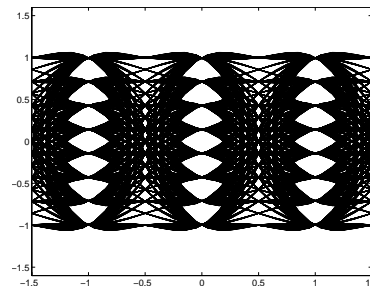
$\alpha = 0$ 0% excess bandwidth



$\alpha = 1$ 100% excess bandwidth



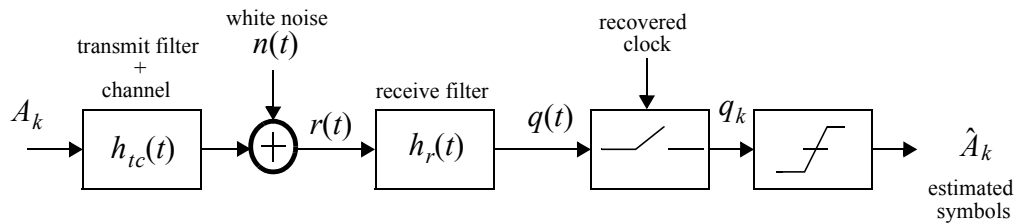
$\alpha = 0.5$ 50% excess bandwidth



$\alpha = 1$ 100% excess bandwidth



Matched-Filter



- For zero-ISI, $h_{tc}(t) \otimes h_r(t)$ satisfies Nyquist criterion.
- For optimum noise performance, $h_r(t)$ should be a ***matched-filter***.
- A matched-filter has an impulse response which is time-reversed of $h_{tc}(t)$

$$h_r(t) = Kh_{tc}(-t) \quad (6)$$

where K is an arbitrary constant.



Matched-Filter (proof)

- Consider isolated pulse case (so no worry about ISI)

$$r(t) = A_0 h_{ic}(t) + n(t) \quad (7)$$

$$q_0 = \int_{-\infty}^{\infty} r(\tau) h_r(t - \tau) d\tau \Big|_{t=0} = \int_{-\infty}^{\infty} r(\tau) h_r(-\tau) d\tau \quad (8)$$

$$q_0 = A_0 \int_{-\infty}^{\infty} h_{ic}(\tau) h_r(-\tau) d\tau + \int_{-\infty}^{\infty} n(\tau) h_r(-\tau) d\tau \quad (9)$$

- Want to maximize signal term to noise term
- Variance of noise is

$$\sigma_n^2 = N_0 \int_{-\infty}^{\infty} h_r^2(-\tau) d\tau \quad (10)$$



Matched-Filter (proof)

- Assuming A_0 and $h_{ic}(t)$ fixed, want to maximize

$$\text{SNR} = \frac{A_0^2 \left[\int_{-\infty}^{\infty} h_{ic}(\tau) h_r(-\tau) d\tau \right]^2}{N_0^2 \int_{-\infty}^{\infty} h_r^2(-\tau) d\tau} \quad (11)$$

- Use Schwarz inequality

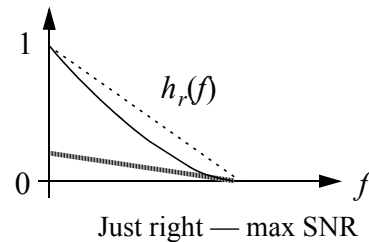
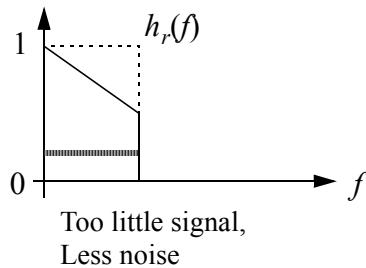
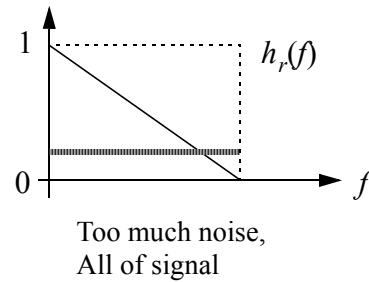
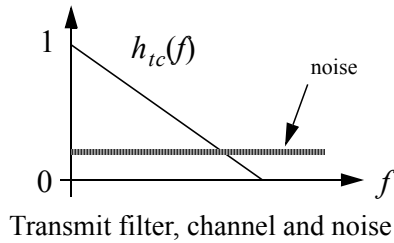
$$\left[\int_a^b f_1(x) f_2(x) dx \right]^2 \leq \left[\int_a^b f_1^2(x) dx \right] \left[\int_a^b f_2^2(x) dx \right] \quad (12)$$

with equality if and only if $f_2(x) = K f_1(x)$

- Maximizing (11) results in $h_r(t) = K h_{ic}(-t)$ — QED



Matched-Filter — Why optimum?



ISI and Noise

- In general, we need the output of a *matched filter* to obey Nyquist criterion
- Frequency response at output of matched filter is $|H_{tc}(j\omega)|^2$ leading to criterion

$$\frac{1}{T} \sum_{m=-\infty}^{\infty} |H_{tc}(j2\pi f + jm2\pi f_s)|^2 = 1 \quad (13)$$

Example

- Assume a flat freq resp channel and raised-cosine pulse is desired at matched-filter output
- Transmit filter should be $\sqrt{\text{raised-cosine}}$
- Receive filter should be $\sqrt{\text{raised-cosine}}$



Gaussian Noise and SNR Requirement



Probability Distribution Function

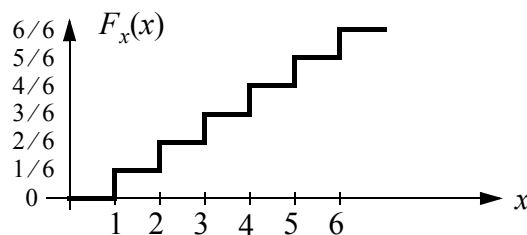
- Consider a random variable X
- Cumulative distribution function (c.d.f.) — $F_x(x)$

$$F_x(x) \equiv P_r(X \leq x) \quad -\infty < x < \infty \quad (14)$$

$$1 \geq F_x(x) \geq 0 \quad (15)$$

Example

- Consider a fair die



Probability Density Function

- Derivative of $F_x(x)$ is p.d.f. defined as $f_x(x)$

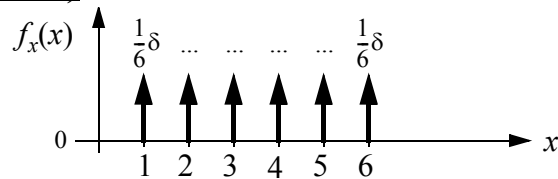
$$f_x(x) \equiv \frac{dF_x(x)}{dx} \quad \text{or} \quad F_x(x) = \int_{-\infty}^x f_x(\alpha) d\alpha \quad (16)$$

- To find prob that X is between x_1 and x_2

$$P_r(x_1 < X \leq x_2) = \int_{x_1}^{x_2} f_x(\alpha) d\alpha \quad (17)$$

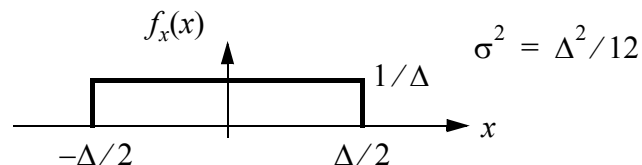
- It is the area under p.d.f. curve.

Example (fair die)



Uniform Distribution

- p.d.f. is a constant
- Variance is given by: $\sigma^2 = \frac{\Delta^2}{12}$ where Δ is range of random variables



- Crest factor: $CF \equiv \frac{\max}{\sigma} = \frac{\Delta/2}{\Delta/\sqrt{12}} = \sqrt{3} = 1.732$

Example

- A uniform random variable chosen between 0 and 1 has a mean, $\mu = 0.5$, and variance, $\sigma^2 = 1/12$

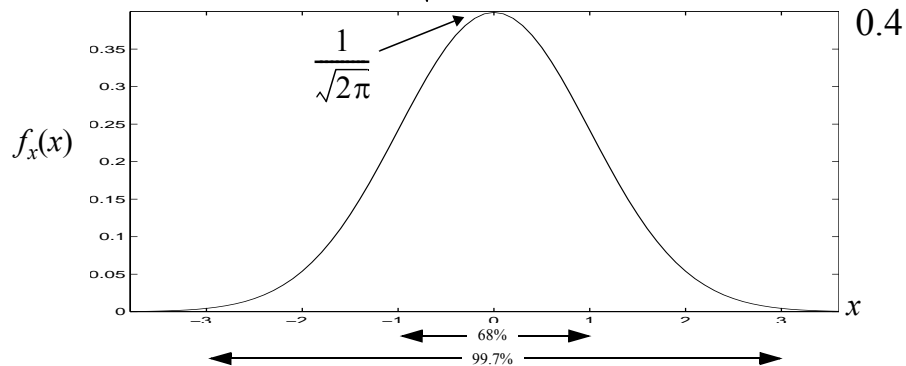


Gaussian Random Variables

Probability Density Function

- Assuming $\sigma^2 = 1$ (i.e. variance is unity) and $\mu = 0$ (i.e. mean is zero) then

$$f_x(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2} \quad (18)$$

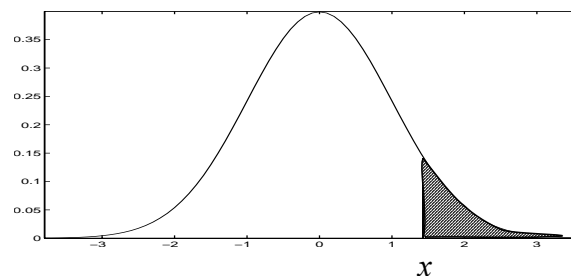


Gaussian Random Variables

- Often interested in how likely a random variable will be in tail of a Gaussian distribution

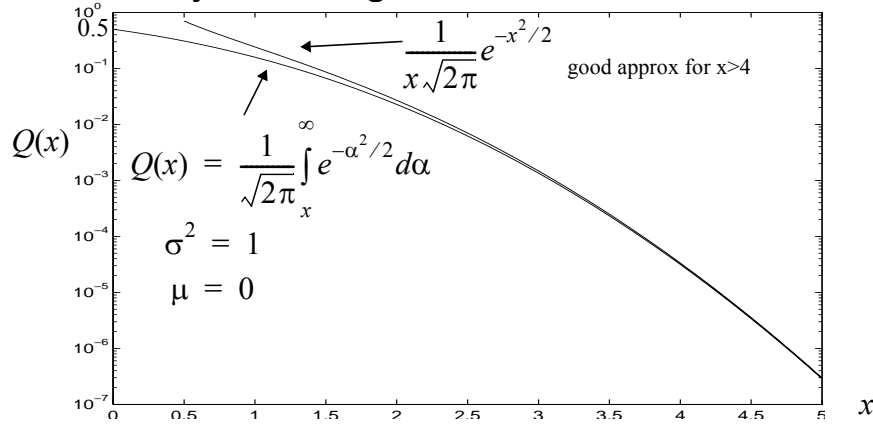
$$Q(x) \equiv P_r(X > x) = \frac{1}{\sqrt{2\pi}} \int_x^{\infty} e^{-\alpha^2/2} d\alpha \quad (19)$$

$$Q(x) = \frac{1}{2} \text{erfc}(x/\sqrt{2}) \quad (20)$$



Gaussian Random Variables

- Probability of X being in tail of Gaussian distribution



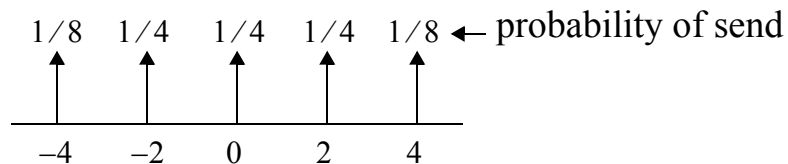
- If $\sigma^2 \neq 1$ or $\mu \neq 0$

$$P_r(X > x) = Q((x - \mu)/\sigma) \quad (21)$$



Example SNR Calculation

- 100Base-T2 for fast-ethernet uses 5-PAM
- Want to calculate the receive SNR needed for a symbol-error-rate of 10^{-10} (assume rest is ideal).



- Signal power, P_s

$$P_s = \frac{1}{4} \times 0W + \frac{1}{2} \times 4W + \frac{1}{4} \times 16W = 6W \quad (22)$$

- Using a reference of $1W$ as 0dB,

$$P_s = 10 \log_{10}(6) = 7.78 \text{dB} \quad (23)$$



Example SNR Calculation

- Assume Gaussian noise added to receive signal.
- Since symbols are distance 2 apart, a noise value greater than 1 will cause an error in receive symbol.
- Want to find σ of Gaussian distribution such that likelihood of random variable greater than 1 is 10^{-10} .
- Recall

$$Q(x/\sigma) = 0.5\text{erfc}((x/\sigma)/\sqrt{2}) \quad (24)$$

- Let $x = 1$ and set

$$2Q(1/\sigma) = 10^{-10} \quad (25)$$

(2 value because variable might be > 1 or < -1)

$$0.5 \times 10^{-10} = Q(1/\sigma) = 0.5\text{erfc}(1/(\sigma\sqrt{2})) \quad (26)$$



Example SNR Calculation

- Trial and error gives $1/(\sigma\sqrt{2}) = 4.57$ implying that $\sigma = 0.1547 = 1/6.46$
- Noise with $\sigma = 0.1547$ has a power of (ref to 1W)

$$P_n = 10\log_{10}(\sigma^2) = -16.2\text{dB} \quad (27)$$

- Finally, SNR needed at receive signal is

$$\text{SNR} = 7.78\text{dB} - (-16.2\text{dB}) = 24\text{dB} \quad (28)$$

- Does not account that large positive noise on +4 signal will **not** cause symbol error (same on -4).
- It is slightly conservative
- BER approx same as symbol error rate if Gray coded



m-PAM

- For m bits/symbol $\Rightarrow 2^m$ levels
- Normalize distance between levels to 2 (so error of 1 causes a symbol error)
- ($m = 1$) $\Rightarrow \pm 1$ ($m = 3$) $\Rightarrow \pm 1, \pm 3, \pm 5, \pm 7$ etc.
- Noise variance of ($\sigma = 0.1547$) $\Rightarrow \text{BER} = 10^{-10}$
- Symbols spaced $\pm 1, \pm 3, \pm 5, \dots, \pm(2^m - 1)$
— average power is: $S_m = (4^m - 1)/3$

$$\text{SNR} = 10\log\left(\frac{S_m}{\sigma^2}\right) = 10\log\left(\frac{4^m - 1}{3\sigma^2}\right) \quad (29)$$



m-PAM

$$\text{SNR} = 10\log\left(\frac{S_m}{\sigma^2}\right) = 10\log\left(\frac{4^m - 1}{3\sigma^2}\right) \quad (30)$$

- equals 23.1 dB for $m = 2$, $\text{BER} = 10^{-10}$
- equals 28.2 dB for $m = 3$, $\text{BER} = 10^{-10}$ (approx +6dB)
- Can show $S_{m+1} = 4S_m + 1$
- Require 4 times more power to maintain same symbol error rate with same noise power (uncoded)
- In other words,
— to send 1 more bit/symbol, need 6dB more SNR (but does not increase bandwidth)



Why Assume Gaussian Noise?

Central-Limit Theorem

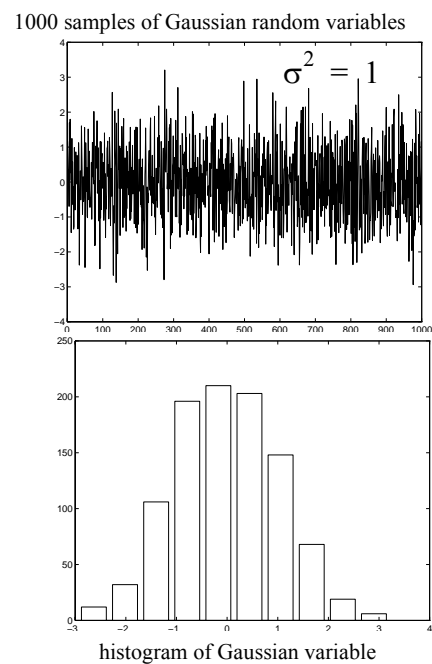
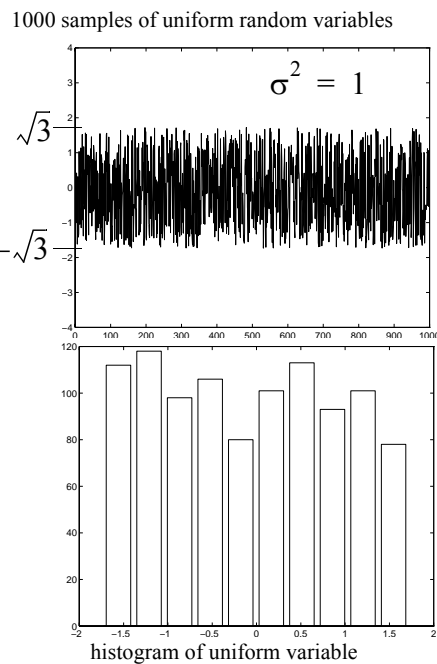
- Justification for modelling many random signals as having a Gaussian distribution

Sum of independent random variables approaches Gaussian as sum increases

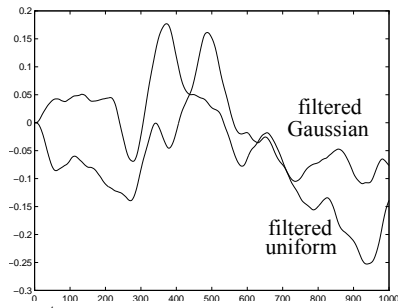
- Assumes random variables have identical distributions.
- No restrictions on original distribution (except finite mean and variance).
- Sum of Gaussian random variables is also Gaussian.



Uniform and Gaussian Signals

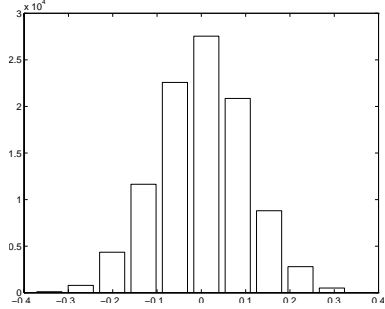


Filtered Random Signals

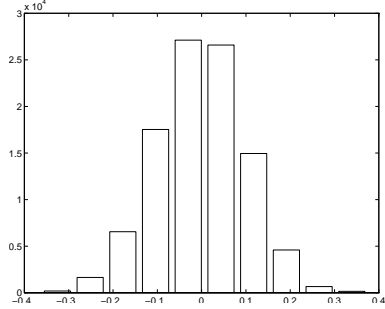


Filtered with 3rd order Butterworth lowpass with cutoff $f_s/200$

No longer independent from sample to sample



histogram of filtered uniform
(100,000 samples)



histogram of filtered Gaussian
(100,000 samples)



Wired Digital Communications



Wired Digital Transmission

Long Twisted-Pair Applications (1km - 6km)

- T1/E1 — 1.5/2Mb/s (2km)
- ISDN — Integrated Services Digital Network
- HDSL — High data-rate Digital Subscriber Line
- ADSL — Asymmetric DSL
- VDSL — Very high data-rate DSL

Short Twisted-Pair Applications (20m - 100m)

- 100Mb/s Fast-Ethernet — TX, T4, T2
- Gigabit Ethernet — Short haul, Long haul

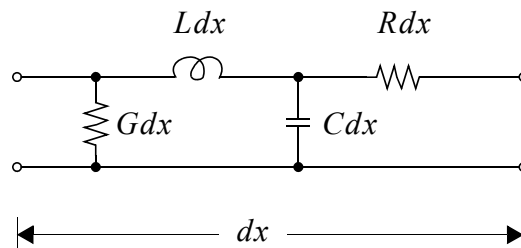
Short Coax (300m)

- Digital video delivery — 300Mb/s - 1.5Gb/s



Cable Modelling

- Modelled as a transmission line.



Twisted-Pair Typical Parameters:

- $R(f) = (1 + j)\sqrt{f/4} \Omega/\text{km}$ due to the skin effect
- $L = 0.6 \text{ mH}/\text{km}$ (relatively constant above 100kHz)
- $C = 0.05 \mu\text{F}/\text{km}$ (relatively constant above 100kHz)
- $G = 0$



Skin Effect

- “Resistance” is not constant with frequency and is complex valued.
- Can be modelled as:

$$R(\omega) = k_R(1+j)\sqrt{\omega} \quad (31)$$

where k_R is a constant given by

$$k_R = \frac{1}{\pi d_c} \left(\frac{\mu}{2\sigma} \right)^{1/2} \quad (32)$$

- d_c is conductor diameter, μ is permeability, σ is conductivity
- Note resistance is inversely proportional to d_c .
- Jordan and Balmain, “Electromagnetic Waves and Radiating Systems”, pg. 563, Prentice-Hall, 1968.



Characteristic Impedance

$$Z_0 = \sqrt{\frac{R+j\omega L}{G+j\omega C}} \quad (33)$$

- Making use of (31) and assuming $G = 0$

$$Z_0 = \left(\frac{k_R \sqrt{\omega} (1+j) + j\omega L}{j\omega C} \right)^{1/2} \quad (34)$$

$$Z_0 = \sqrt{\frac{L}{C}} \left(1 + \frac{k_R}{L\sqrt{\omega}} (1-j) \right)^{1/2} \quad (35)$$

Now using approx $(1+x)^{1/2} \approx 1+x/2$ for $x \ll 1$

$$Z_0 \approx \sqrt{\frac{L}{C}} + \frac{k_R}{2\sqrt{\omega LC}} (1-j) \quad (36)$$

- At high freq, Z_0 appears as constant value $\sqrt{L/C}$



Characteristic Impedance

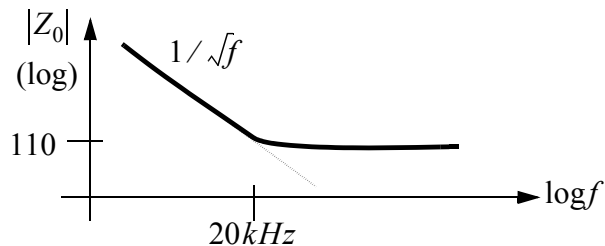
- From (33), when $\omega L \gg R$ (typically $\omega \gg 2\pi \times 16\text{kHz}$)

$$Z_{0h} = \sqrt{\frac{L}{C}} \quad (37)$$

resulting in

$$Z_{0h} \approx 110 \Omega \quad (38)$$

- Thus, when terminating a line, a resistance value around 110Ω should be used.



Cable Transfer-Function

- When properly terminated, a cable of length d has a transfer-function of

$$H(d, \omega) = e^{-d\gamma(\omega)} \quad (39)$$

where $\gamma(\omega)$ is given by

$$\gamma(\omega) = \sqrt{(R + j\omega L)(G + j\omega C)} \quad (40)$$

- Breaking $\gamma(\omega)$ into real and imaginary parts,

$$\gamma(\omega) \equiv \alpha(\omega) + j\beta(\omega) \quad (41)$$

$$H(d, \omega) = e^{-d\alpha(\omega)} e^{-jd\beta(\omega)} \quad (42)$$

- $\alpha(\omega)$ determines **attenuation**.
- $\beta(\omega)$ determines **phase**.



Cable Transfer-Function

- Assuming $G = 0$, then from (40)

$$\gamma = (j\omega CR - \omega^2 LC)^{1/2} \quad (43)$$

- Substituting in (31)

$$\gamma = (j\omega^{1.5} k_R C(1+j) - \omega^2 LC)^{1/2} \quad (44)$$

$$\gamma = j\omega\sqrt{LC} \left(1 + \frac{k_R}{L\sqrt{\omega}}(1-j)\right)^{1/2} \quad (45)$$

Now using approx $(1+x)^{1/2} \approx 1+x/2$ for $x \ll 1$

$$\gamma \approx \frac{k_R}{2} \sqrt{\frac{\omega C}{L}} + j \left(\omega\sqrt{LC} + \frac{k_R}{2} \sqrt{\frac{\omega C}{L}} \right) \quad (46)$$



Cable Attenuation

- Equating (41) and (46)

$$\alpha(\omega) \approx \frac{k_R}{2} \sqrt{\frac{C}{L}} \times \sqrt{\omega} \quad (47)$$

- Therefore gain in dB is

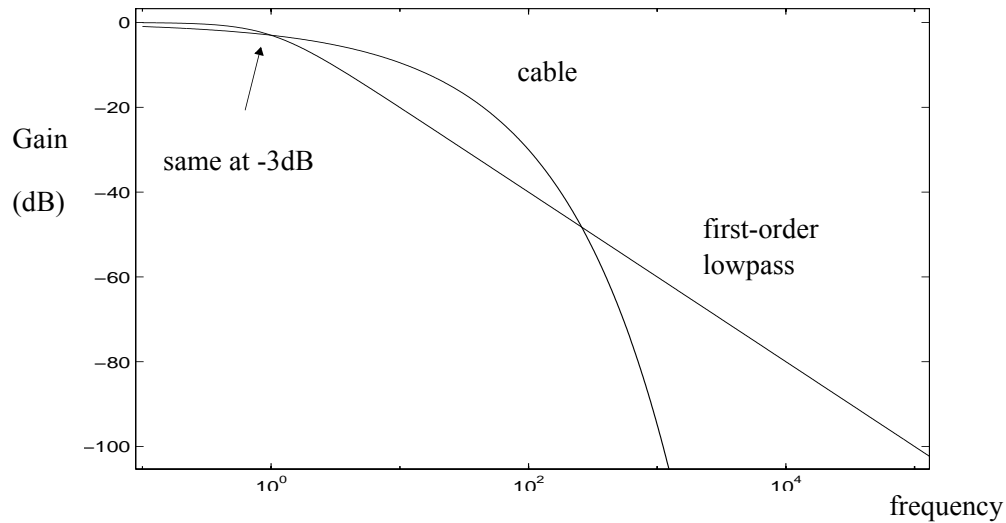
$$H_{dB}(d, \omega) \approx -8.68d \times \frac{k_R}{2} \sqrt{\frac{C}{L}} \times \sqrt{\omega} \quad (48)$$

- Note that attenuation in dB is proportional to cable length (i.e. 2x distance doubles attenuation in dB)
- Can reduce attenuation by using a larger diameter cable
- Attenuation proportional to root-frequency



Cable Attenuation

- Gain in dB is proportional to \sqrt{f} due to skin effect.



- Do not confuse with 1/f noise slow frequency roll-off.



Cable Phase

- Equating (41) and (46)

$$\beta(\omega) \approx \omega \sqrt{LC} + \frac{k_R}{2} \sqrt{\frac{C}{L}} \times \sqrt{\omega} \quad (49)$$

- The linear term usually dominates
- The linear term implies a constant group delay.
- In other words, the linear term simply accounts for the delay through the cable.
- Ignoring linear phase portion, remaining phase is proportional to \sqrt{f} .
- Note it has the same multiplying term as attenuation.



IIR Filter Cable Match using Matlab

```
% this program calculates an iir num/den transfer-function
% approx for a transmission line with exp(sqrt(s)) type response.
clear;

% Order of IIR filter to match to cable
% nz is numerator order and np is denominator order
nz = 9;
np = 10;

% important parameters of cable
c = 0.05e-6 % capacitance per unit length in farads/km
l = 0.6e-3 % inductance per unit length in henries/km
kr = 0.25 % resistance per unit length in ohms/km (times (1+j)*sqrt(omega))
d = 0.1 % cable length in km
% above values adjusted to obtain -20dB atten for 100m at 125MHz
k_cable = (kr/2)*sqrt(c/l);

% the frequency range for finding tf of cable
fmin=1;
fmax=1e9;
```



```
% specify frequency points to deal with
nmax=1000;
f=logspace(log10(fmin), log10(fmax), nmax);
w=2*pi*f;
s=j*w;

% 'cable' is desired outcome in exponential form
cable = exp(-d*k_cable*sqrt(2)*sqrt(s));

% Perform IIR approximate transfer-function match
% Since invfreqs minimizes (num-cable*den)
% first need an approximate den so that it can be used
% as a freq weighting to minimize (num/den - cable)
[num,den]=invfreqs(cable,w,nz,np, 1./w);
[denor]=freqs(den,1,w);
% re-iterate process with weighting for the denominator
% which now minimizes (num/den - cable)
[num,den]=invfreqs(cable,w,nz,np, (1./denor).^2);
[denor]=freqs(den,1,w);
[num,den]=invfreqs(cable,w,nz,np, (1./denor).^2);

% find approximate transfer function 'cable_approx' to 'cable'
[cable_approx]=freqs(num,den,w);
```



```

% also find pole-zero model
[Z,p,k]=tf2zp(num,den);

% PLOT RESULTS
clf;
figure(1);
subplot(211);
semilogx(f,20*log10(abs(cable)), 'r');
hold on;
semilogx(f,20*log10(abs(cable_approx)), 'b');
title('Cable Magnitude Response');
xlabel('Freq (Hz)');
ylabel('Gain (dB)');
grid;

hold off;
subplot(212);
semilogx(f,angle(cable)*180/pi, 'r');
hold on;
semilogx(f,angle(cable_approx)*180/pi, 'b');
title('Cable Phase Response');
xlabel('Freq (Hz)');

```



```

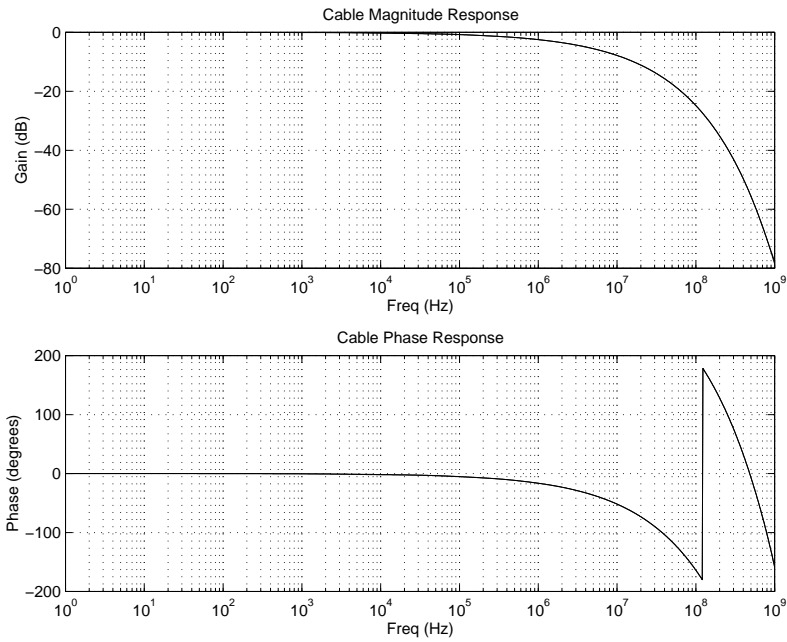
ylabel('Phase (degrees)');
grid;

hold off;
figure(2);
subplot(211);
semilogx(f,20*log10(abs(cable)./abs(cable_approx)));
title('Gain Error Between Cable and Cable_approx');
xlabel('Freq (Hz)');
ylabel('Gain Error (dB)');
subplot(212);
semilogx(f,(angle(cable)-angle(cable_approx))*180/pi);
title('Phase Error Between Cable and Cable_approx');
xlabel('Freq (Hz)');
ylabel('Phase Error (degrees)');
grid;

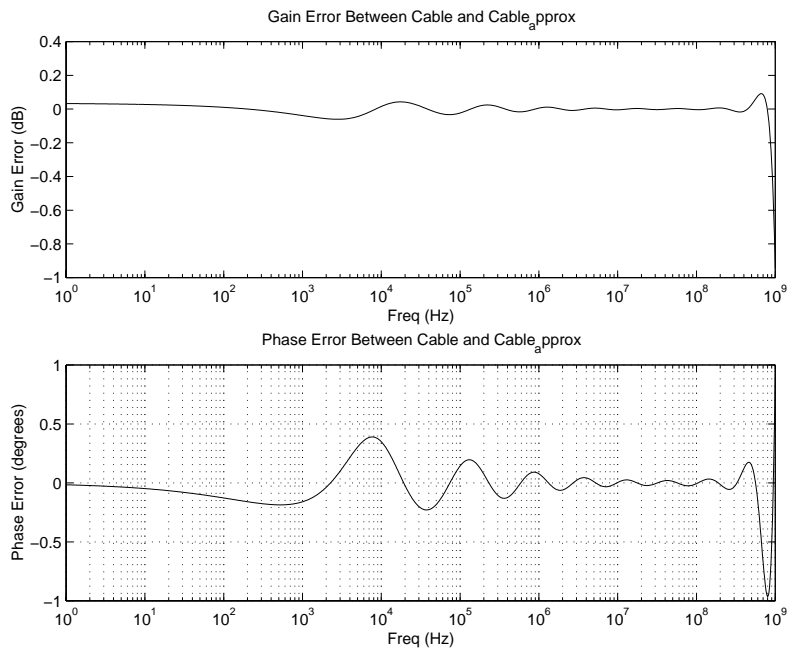
```



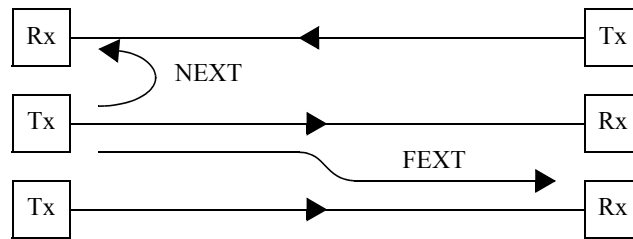
Cable Response



IIR Matching Results



Near and Far End Crosstalk

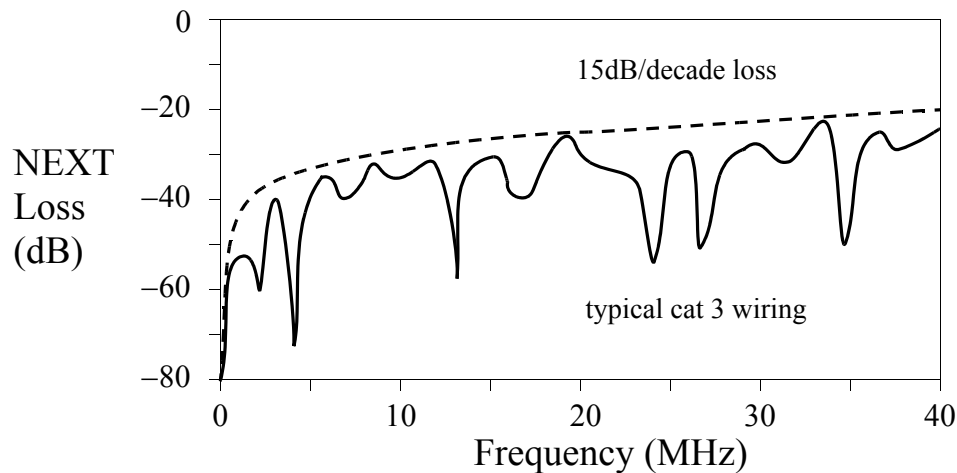


- In FEXT, interferer and signal both attenuated by cable
- In NEXT, signal attenuated but interferer is coupled directly in.
- When present, NEXT almost always dominates.
- Can cancel NEXT if nearby interferer is known.
- Envelope of squared gain of NEXT increases with $f^{1.5}$



Twisted-Pair Crosstalk

- Crosstalk depends on turns/unit length, insulator, etc.
- Twisted-pairs should have different turns/unit length within same bundle



Transformer Coupling

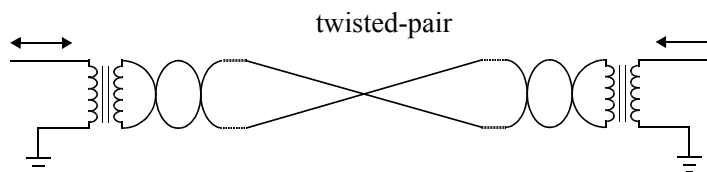
- Almost all long wired channels (>10m) are AC coupled systems
- AC coupling introduces *baseline wander* if random PAM sent
- A long string of like symbols (for example, +1) will decay towards zero degrading performance
- Requires baseline wander correction (non-trivial)
- Can use passband modulation schemes (CAP, QAM, DMT)
- *Why AC couple long wired channels??*



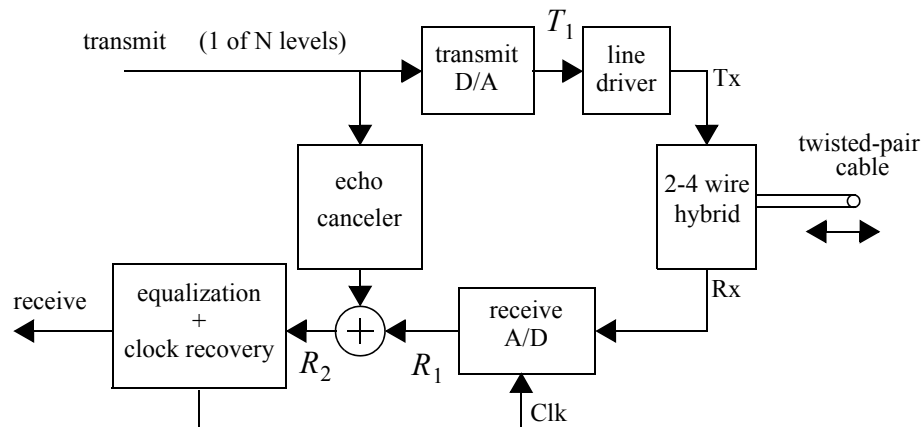
Transformer Coupling

Eliminates need for similar grounds

- If ground potentials not same — large ground currents
- ### **Rejects common-mode signals**
- Transformer output only responds to differential signal current
 - Insensitive to common-mode signal on both wires



Generic Wired PAM Transceiver



- Look at approaches for each block



HDSL Application

- 1.544Mb/s over 4.0km of existing telephone cables.
- Presently 4-level PAM code (2B1Q) over 2 pairs (a CAP implementation also exists).
- Symbol-rate is 386 ksymbols/s

Possible Bridged-Taps

- Can have unterminated taps on line
- Modelling becomes more complicated but DFE equalizes effectively
- Also causes a wide variation in input line impedance to which echo canceller must adapt — difficult to get much analog echo cancellation



HDSL Application

- Symbol-rate is 386 ksymbols/s

Received Signal

- For $d = 4\text{km}$, a 200kHz signal is attenuated by 40dB .
- Thus, high-freq portion of a 5Vpp signal is received as a 50mVpp signal — *Need effective echo cancellation*

Transmit Path

- Due to large load variations, echo cancellation of analog hybrid is only 6dB
- To maintain 40dB SNR receive signal, linearity and noise of transmit path should be better than 74dB.



ISDN Application

- Similar difficulty to HDSL but lower frequency
- 160kb/s over 6km of 1 pair existing telephone cables
- 4-level PAM coding — 2B1Q
- Receive signal at 40kHz atten by 40dB
- Requires highly linear line-drivers + A/D converters for echo cancellation (similar to HDSL)



Fast-Ethernet Application

CAT3	CAT5
$H_{dB}(f) = 2.32\sqrt{f} + 0.238f$	$H_{dB}(f) = 1.967\sqrt{f} + 0.023f + 0.05/\sqrt{f}$
12.5MHz \leftrightarrow 11dB	12.5MHz \leftrightarrow 7dB
crosstalk worse	crosstalk better

100Base-T4

- 4 pair CAT3 — 3 pair each way, 25MS/s with coding

100Base-TX

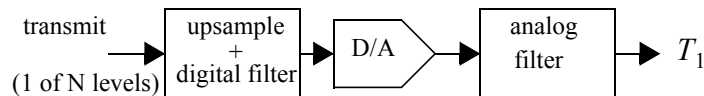
- 2 pair CAT5 — 3 level PAM to reduce radiation

100Base-T2

- 2 pair CAT3 — 5x5 code, 25MS/s on each pair



Typical Transmit D/A Block



- Polyphase filter to perform upsampling+filtering

HDSL

- D/A and filter needs better than 12-bit linearity
- Might be an oversampled 1-bit DAC
- One example: $\uparrow 16$; 48 tap FIR; $\uparrow 4$; $\Delta\Sigma$ DAC

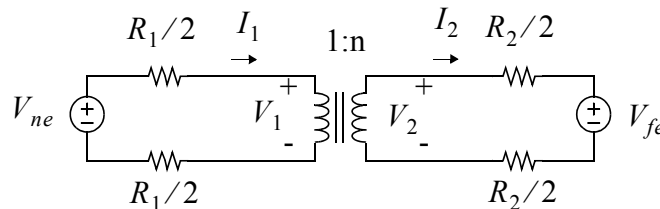
Fast-Ethernet

- Typically around 35 dB linearity + noise requirement
- 100Base-T2 example: $\uparrow 3$; simple FIR; 75MHz 4-bit DAC; 3rd-order LP cont-time filter



Line Drivers

- Line driver supplies drive current to cable.
- Commonly realized as voltage buffers.
- Often the most challenging part of analog design.
- Turns ratio of transformer determines equivalent line impedance.



$$V_{ne} = \frac{2}{n} V_2$$

$$V_1 = V_2/n$$

$$I_1 = nI_2$$

$$R_1 = R_2/n^2$$

Typical Values

$$R_2 = 100\Omega$$

$$V_2 = \pm 2.5V$$

$$I_2 = \pm 25mA$$



Line Driver Efficiency

- Efficiency improves as power supply increased

Example (assume can drive within 1V of supplies)

- From typical values, max power delivered by line driver is

$$P_{\text{line+R}} = 2 \times 2.5 \times 25mA = 125mW$$

12V Case

- Consider 12V supply — use $n = 0.5$, $V_{ne, \text{max}} = 10V$,
 $I_{1, \text{max}} = 12.5mA$ leading to $P = 12 \times 12.5mA = 150mW$
 (and drive an 800 ohm load)

3V Case

- Consider 3V supply — use $n = 5$, $V_{ne, \text{max}} = 1V$,
 $I_{1, \text{max}} = 125mA$ leading to $P = 3 \times 125mA = 375mW$
 (and drive an 8 ohm load!!!)



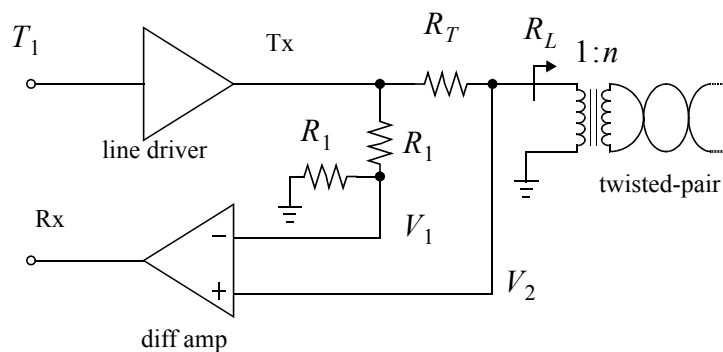
Line Driver

- In CMOS, W/L of output stage might have transistors on the order of 10,000!
- Large sizes needed to ensure some gain in final stage so that feedback can improve linearity — might be driving a 30 ohm load
- When designing, ensure that enough phase margin is used for the wide variation of bias currents
- Nested Miller compensation has been successfully used in HDSL application with class AB output stage
- Design difficulties will increase as power supplies decreased



2-4 Wire Hybrids

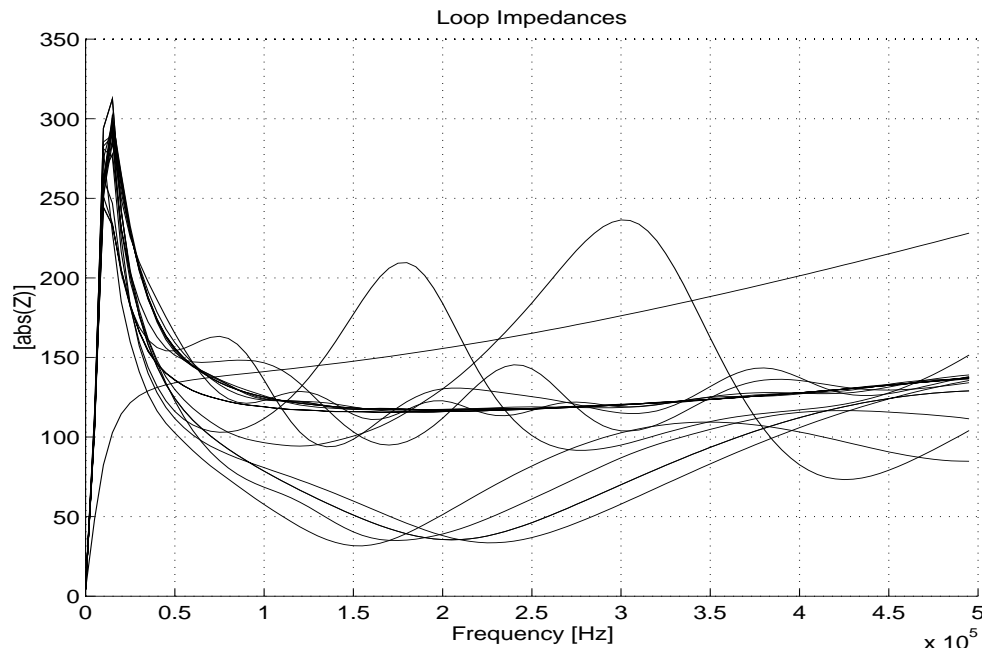
- Dual-duplex often used to reduce emission.
- However, dual-duplex requires hybrids and echo cancellation.



- If $R_L = R_T$, no echo through hybrid
- Can be large impedance variation.



Typical HDSL Line Impedances



Hybrid Issues

- Note zero at dc and pole at 10kHz.
- Low frequency pole causes long echo tail (HDSL requires 120 tap FIR filter)

Alternatives

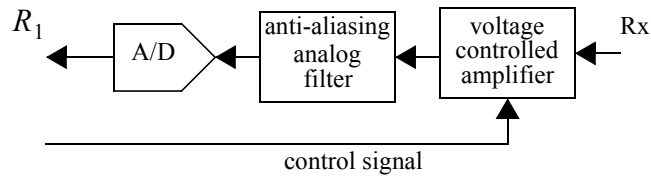
- Could eliminate R_1 circuit and rely on digital echo cancellation but more bits in A/D required.

OR

- Can make R_1 circuit more complex to ease A/D specs.
- Less echo return eases transmit linearity spec.
- Might be a trend towards active hybrids with or without extra A/D and D/A converters (particularly for higher speeds).



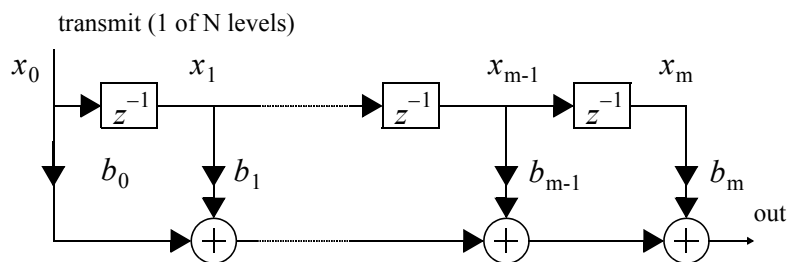
Typical Receive A/D



- Often, VGA is controlled from digital signal.
- Anti-aliasing can be simple in oversampled systems.
- Continuous-time filters are likely for fast-ethernet
- Example: 100Base-T2 suggests a 5'th order cont-time filter at 20MHz with a 6-bit A/D at 75MHz.
- Challenge here is to keep size and power of A/D small.



Echo Cancellation



$$b_i(k+1) = b_i(k) + \mu e(k)x_i(k) \quad \text{LMS}$$

- Typically realized as an adaptive FIR filter.
- Note input is transmit signal so delay lines and multiplies are trivial.
- HDSL uses about a 120 tap FIR filter
- Coefficient accuracy might be around 20 bits for dynamic range of 13 bits.



Echo Cancellation

- Fast-ethernet might be around 30 taps and smaller coefficient accuracy
- Can also perform some NEXT cancellation if signal of nearby transmitter is available (likely in 100Base-T2 and gigabit ethernet)

Alternatives

- Higher data rates may have longer echo tails.
- Might go to FIR/IIR hybrid to reduce complexity.
- Non-linear echo cancellation would be VERY useful in reducing transmit linearity spec.
- However, these non-linearities have memory and thus Volterra series expansions needed.



Equalization

HDSL

- Echo canceller required *before* equalization so fractional spaced equalizer not practical
- Typically 9 tap FFE and 120 tap DFE
- Long DFE also performs dc recovery (baseline wander)

Fast Ethernet

- Often fractional-spaced EQ - 30 taps
- DFE — 20 taps (dc recovery)

