

ECE 454

Computer Systems Programming

Compiler Optimizations

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Content

- History and overview of compilers
- Basic compiler optimizations
- Program optimizations
- Advanced optimizations
 - Parallel unrolling
 - Profile-directed feedback

A Brief History of Compilation

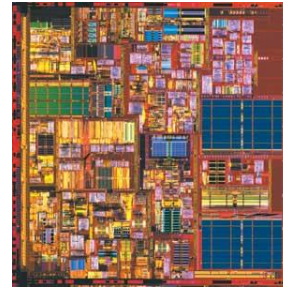
In the Beginning...

Programmer

```
1010010010  
0101101010  
1010010100  
1010001010  
...
```

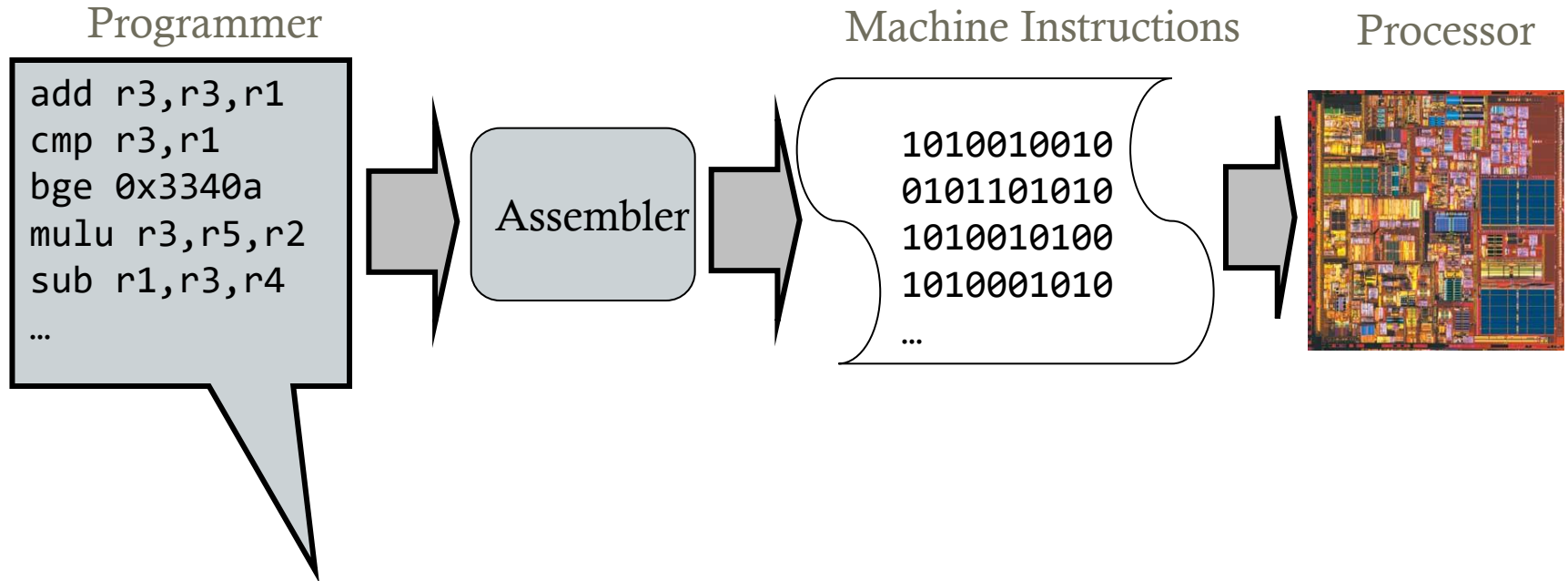


Processor



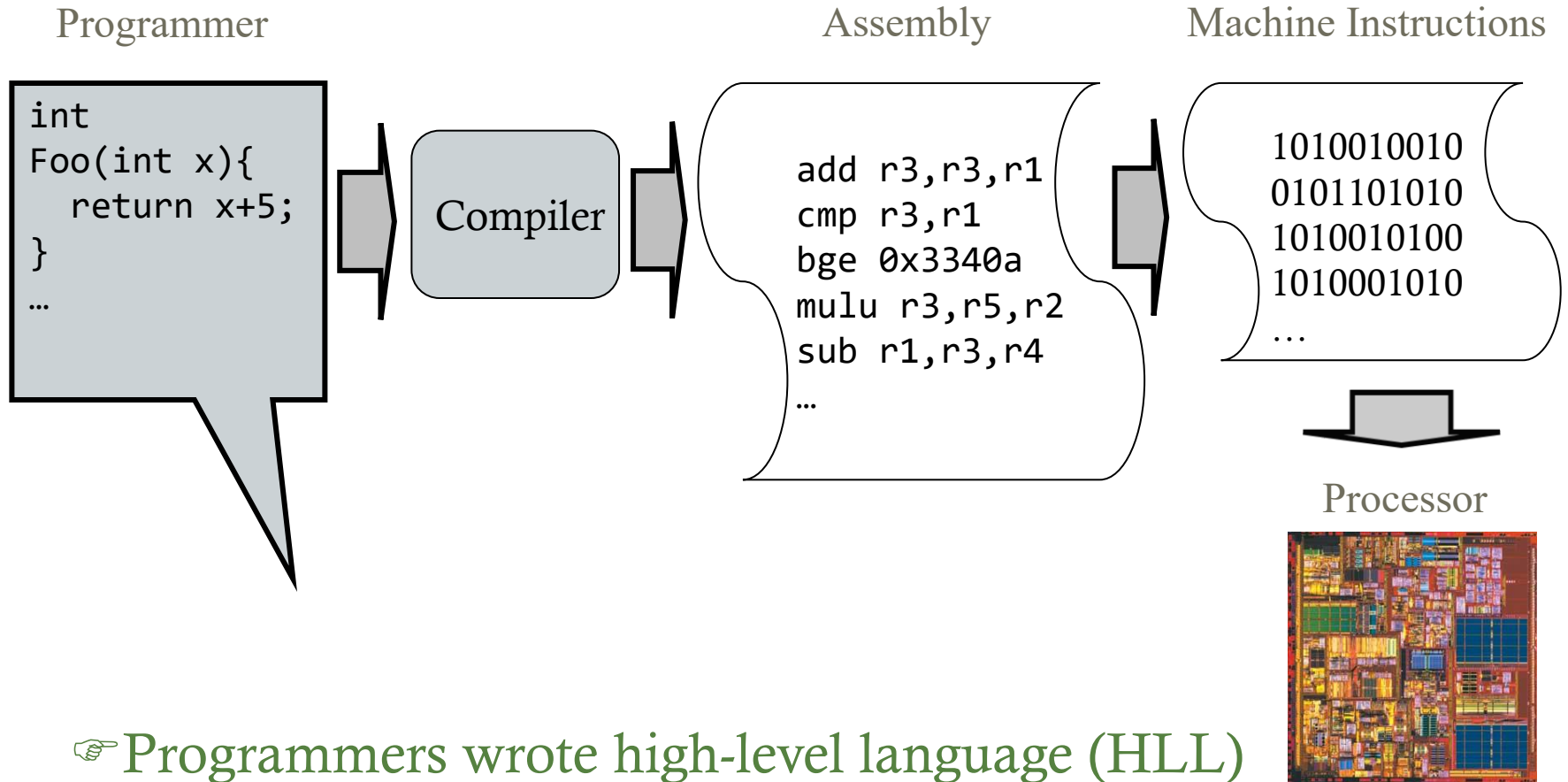
👉 Programmers wrote machine instructions

Then Came the Assembler



👉 Programmers wrote human-readable assembly

Then Came the Compiler

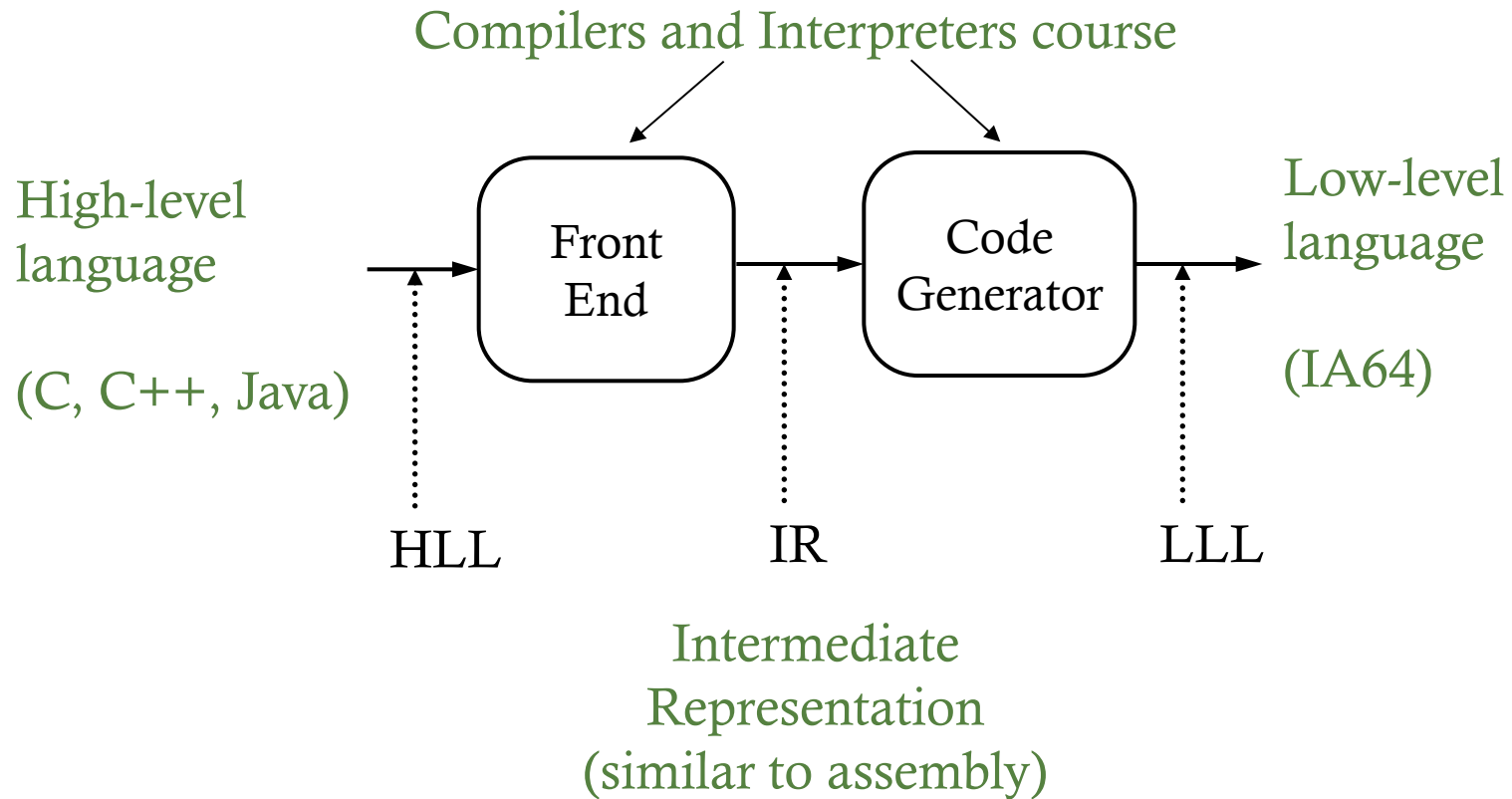


Overview of Compilers

Goals of a Compiler

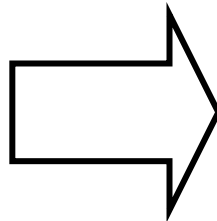
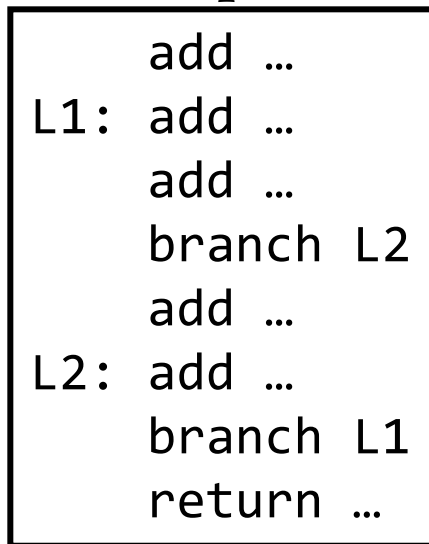
- Correct program executes correctly
- Provide support for debugging incorrect programs
- Program executes fast
- Compilation is fast?
- Small code size?
- More energy efficient program?

Inside a Basic Compiler

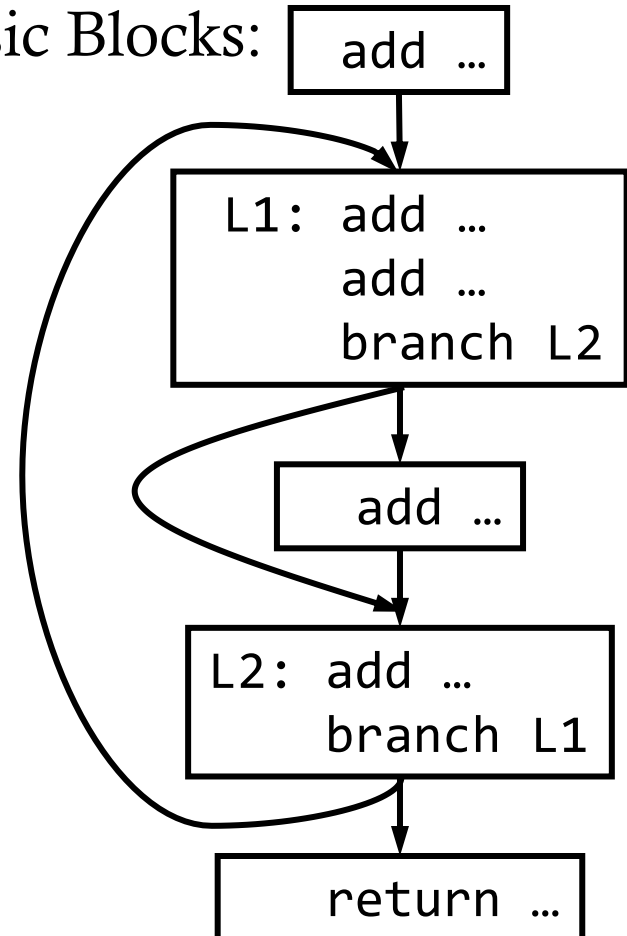


Control Flow Graph: (how a compiler sees your program)

Example IR:



Basic Blocks:



Basic Block: a group of consecutive instructions with a single entry point and a single exit point

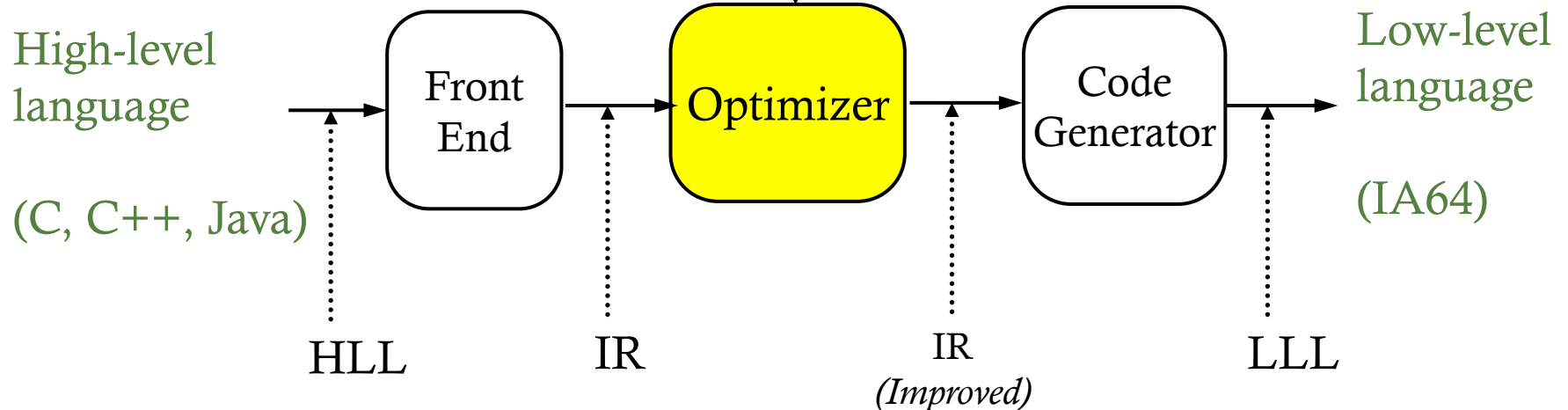
Data Flow Analysis

- Many compiler optimizations (discussed later) use a technique called **data flow analysis**
- Basic idea
 - Analyse and summarize the effects of instructions in a basic block
 - Use CFG to propagate these effects to succeeding basic blocks
- E.g., **reaching definition** data flow analysis
 - Calculates for each program point the set of definitions (program points) that **may** potentially reach this program point

```
1: if b==4 then           // BB1
2:     a = 5;             // BB2
3: else
4:     a = 3;             // BB3
5: endif
6: if a < 4 then ...      // BB4
```

Inside an Optimizing Compiler

CSCD70/ ECE540 Optimizing Compilers



Performance Optimization: 3 Requirements

- Preserve correctness
 - The speed of an incorrect program is irrelevant
- Improve performance of average case
 - Optimized program may be worse than original if unlucky
- Be “worth the effort”
 - Is this example worth it?
 - 1 person-year of work to implement compiler optimization
 - 2x increase in compilation time
 - 0.1% improvement in speed

How do Optimizations Improve Performance?

- Recall

$$\text{Execution_time} = \text{num_instructions} * \text{CPI} * \text{time/cycle}$$

- Fewer instructions

- Use optimized sequence of instructions
- Use new instructions

- Fewer cycles per instruction

- Schedule instructions to avoid hazards
- Improve cache/memory behavior
 - E.g., prefetching, code and data locality

Role of Optimizing Compilers

- Provide efficient mapping of program to machine instructions
 - Eliminate minor inefficiencies
 - Register allocation
 - Instruction selection
 - Instruction scheduling
- Don't (usually) improve asymptotic efficiency
 - Up to programmer to select best overall algorithm
 - Big-O savings are (often) more important than constant factors
 - But constant factors also matter

Limitations of Optimizing Compilers

- Operate under fundamental constraints
 - Must not cause any change in program behavior under any possible condition
- Most analysis is performed only within procedures
 - Inter-procedural analysis is too expensive in most cases
- Most analysis is based only on static information
 - Compiler has difficulty anticipating run-time inputs
- When in doubt, the compiler must always be conservative

Role of the Programmer

- How should I write my programs, given that I have a good, optimizing compiler?
- Don't: smash code into oblivion
 - Hard to read, maintain, assure correctness

Role of the Programmer

- How should I write my programs, given that I have a good, optimizing compiler?
- Do:
 - Select best algorithm
 - Write code that's readable and maintainable
 - Procedures, recursion
 - Even though these may slow down code
 - Focus on inner loops
 - Do detailed optimizations where code will be executed repeatedly
 - Will get most performance gain here
 - Eliminate optimization blockers
 - Allows compiler to do its job!

Basic Compiler Optimizations

Compiler Optimizations


- Machine independent (apply equally well to most CPUs)
 - Constant propagation
 - Constant folding
 - Copy propagation
 - Common subexpression elimination
 - Dead code elimination
 - Loop invariant code motion
 - Function inlining

Compiler Optimizations

- Machine dependent (apply differently to different CPUs)
 - Instruction selection and scheduling
 - Loop unrolling
 - Parallel unrolling
- Possible to do all these optimizations manually, but much better if compiler does them
 - Many optimizations make code less readable/maintainable


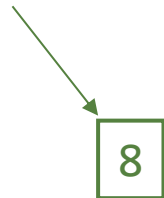
Constant Propagation (CP)

- Replace variables with constants when possible

```
a = 5;  
b = 3;  
:  
:  
n = a + b;   
for (i = 0 ; i < n ; ++i) {  
:  
}
```

Constant Folding (CF)

- Evaluate expressions containing constants

```
      :  
      :  
      :  
      :  
n = 5 + 3;   
for (i = 0 ; i < n ; ++i) {  
      :  
}  

```

- Can lead to further optimization
 - E.g., another round of constant propagation

Common Sub-Expression Elimination (CSE)

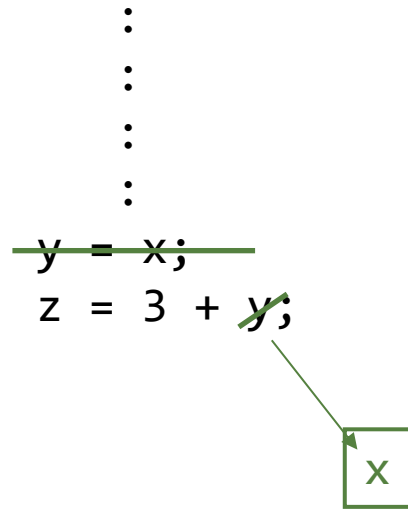
- Try to only compute a given expression once

$a = c * d;$		$a = c * d;$
\vdots	\Rightarrow	\vdots
\vdots		\vdots
$d = (c * d + t) * u$		$d = (a + t) * u$

- Need to ensure the variables have not been modified

Copy Propagation

- Replace occurrences of target of direct assignment with corresponding value



- Often used after common sub-expression elimination and other optimizations

Dead Code Elimination (DCE)

- Compiler can determine if certain code will never execute

```
debug = 0; // set to false      debug = 0;
  :
if (debug) {
  :
}                                ⇒
a = f(b);                       a = f(b);
```

- **Compiler will remove that code**
 - You don't have to worry about such code impacting performance
 - Makes it easier to have readable/debugable programs

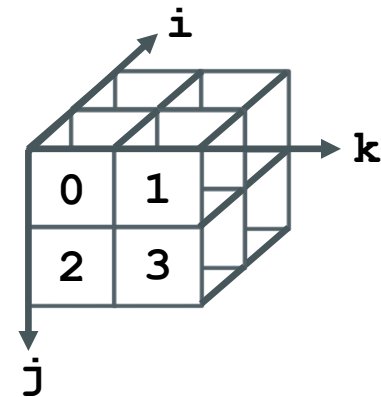
Loop Invariant Code Motion (LICM)

- Loop invariant: value does not change across iterations
- LICM: moves invariant code out of the loop
- Leads to significant performance win

Loop Invariant Code Motion (LICM)

- Consider this triply nested loop

```
for (i=0; i < I; ++i) {  
    for (j=0; j < J; ++j) {  
        for (k=0 ; k < K; ++k) {  
            a[i][j][k] = i*j*k;  
        }  
    }  
}
```



- In C, a multi-dimensional array is stored in row-major order

a[0][0][0]	a[0][0][1]	...	a[0][0][K-1]	a[0][1][0]	...	a[I-1][J-1][0]	..	a[I-1][J-1][K-1]
------------	------------	-----	--------------	------------	-----	----------------	----	------------------

```
char a[I][J][K];
```

```
addr of a[i][j][k] = (addr of a) + (i x J x K) + (j x K) + (k)
```

Loop Invariant Code Motion (LICM)

addr of $a[i][j][k] = (\text{addr of } a) + (i \times J \times K) + (j \times K) + (k)$

```
for (i=0; i < I; ++i) {  
  for (j=0; j < J; ++j) {  
    for (k=0 ; k < K; ++k) {  
      a[i][j][k] = i*j*k;  
    }  
  }  
}  
  
⇒  
  
for (i = 0; i < I; ++i) {  
  t1 = a + i * J * K; // t1=a[i];  
  for (j = 0; j < J; ++j) {  
    t2 = t1 + j * K; // t2=t1[j];  
    for (k = 0 ; k < K; ++k) {  
      t2[k] = i * j * k;  
    }  
  }  
}
```

Loop Invariant Code Motion (LICM)

addr of $a[i][j][k] = (\text{addr of } a) + (i \times J \times K) + (j \times K) + (k)$

```
for (i=0; i < I; ++i) {  
  for (j=0; j < J; ++j) {  
    for (k=0 ; k < K; ++k) {  
      a[i][j][k] = i*j*k;  
    }  
  }  
}  
  
⇒  
  
for (i = 0; i < I; ++i) {  
  t1 = a + i * J * K; // t1=a[i];  
  for (j = 0; j < J; ++j) {  
    t2 = t1 + j * K; // t2=t1[j];  
    tmp = i * j;  
    for (k = 0 ; k < K; ++k) {  
      t2[k] = tmp * k;  
    }  
  }  
}
```

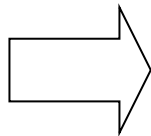
- When $I=J=K=100$, inner loop will execute 1,000,000 times
 - Many of the computations in the inner loop are moved out
 - Improves performance dramatically

Function Inlining

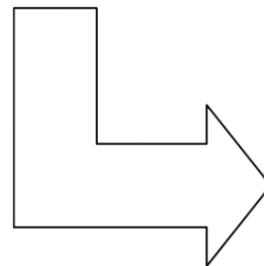
- A function call site is replaced with the body of the function

```
foo(int z){  
    int m = 5;  
    return z + m;  
}
```

```
main(){  
    ...  
    x = foo(x);  
    ...  
}
```



```
main(){  
    ...  
    {  
        int foo_z = x;  
        int foo_m = 5;  
        int foo_return = foo_z + foo_m;  
        x = foo_return;  
    }  
    ...  
}
```



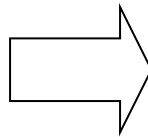
```
main(){  
    ...  
    x = x + 5;  
    ...  
}
```

Function Inlining

- **Performance**
 - Eliminates call/return overhead
 - Can expose potential optimizations
 - Can be hard on instruction-cache if many copies made
 - Code size can increase if large procedure body and many calls
- **As a programmer**
 - A good compiler should inline for best performance
 - Feel free to use procedure calls to make your code readable!

Loop Unrolling

```
j = 0;
while (j < 100){
    a[j] = b[j+1];
    j += 1;
}
```



```
j = 0;
while (j < 99){
    a[j] = b[j+1];
    a[j+1] = b[j+2];
    j += 2;
}
```

- Reduces loop overhead, why?
 - Fewer adds to update j
 - Fewer loop condition tests
 - Reduces branch penalties
- Enables more aggressive instruction scheduling
 - I.e., more instructions in loop basic block for scheduler to move around

Summary: gcc Optimization Levels

- -g: Include debug information, no optimization
- -O0: Default, no optimization
- -O1: Do optimizations that don't take too long
 - CP, CF, CSE, DCE, LICM, inline functions called once
- -O2: Take longer optimizing, more aggressive scheduling
 - E.g., inline small functions
- -O3: Make space/speed trade-offs
 - Can increase code size, loop unrolling, more inlining
- -Os: Optimize program size