

# Jitter Equalization for Binary Baseband Communication

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# Outline

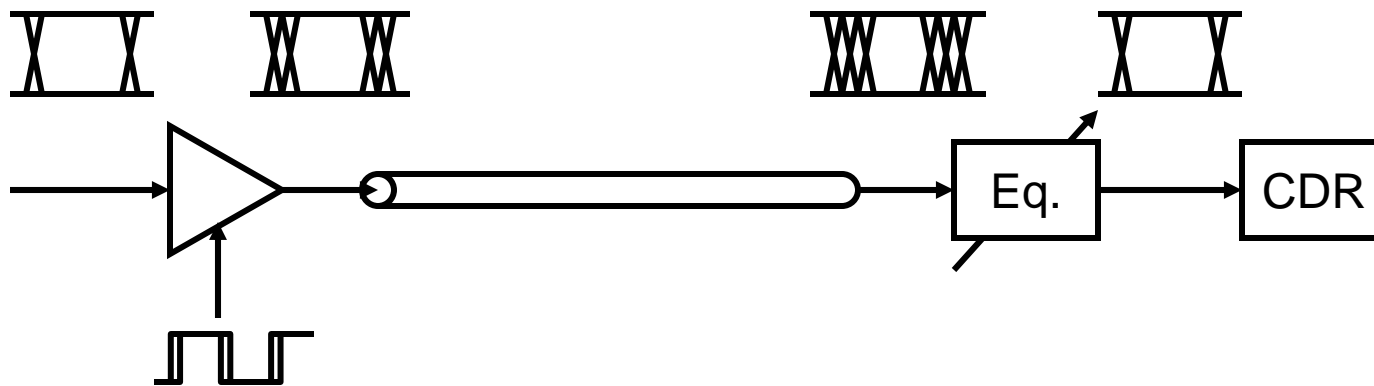
- Problem definition
- Review of LMS algorithm
- Proposed jitter equalization
- Simulations

# Problem definition

- Sources of jitter:

- Transmitter, Receiver

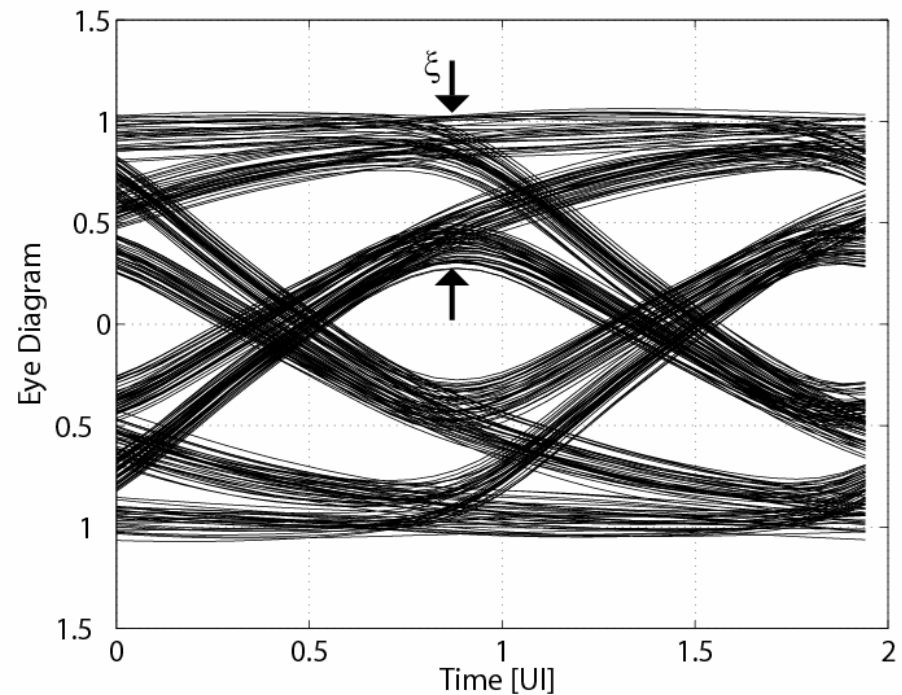
- Channel  $\Rightarrow$  Intersymbol interference**



- Goal: To adapt the equalizer parameters to minimize jitter at the equalizer output

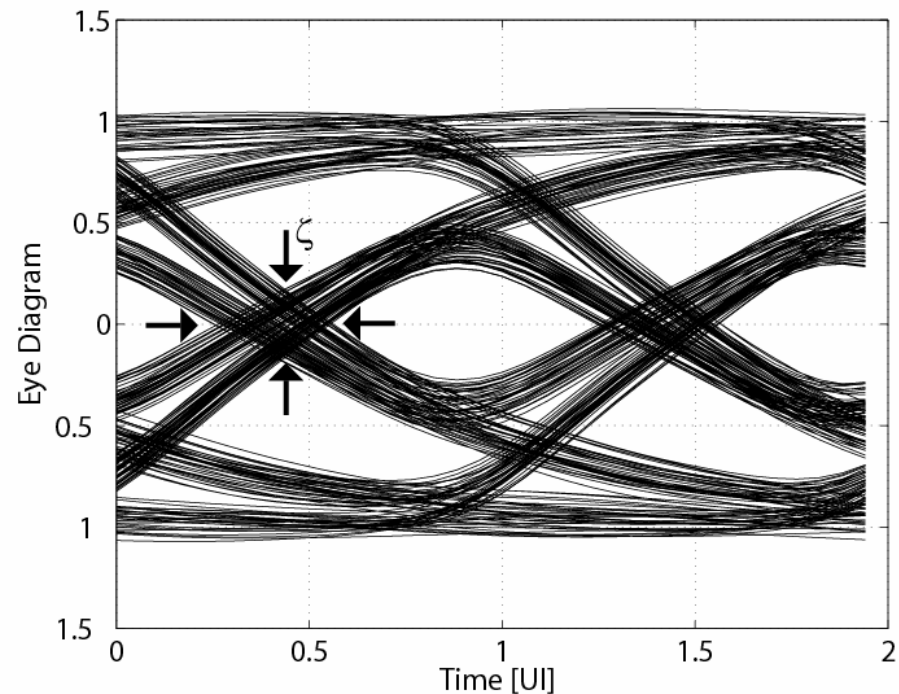
# LMS algorithm

- Maximizes vertical eye opening
- Minimizes  $\xi = E[e^2]$  @ centre of eye



# Jitter Equalization

- Instead, we want to maximize the **horizontal** eye opening
- Minimize ISI at the zero crossings
- Minimize  $\zeta = E[e^2]$  @ zero crossings

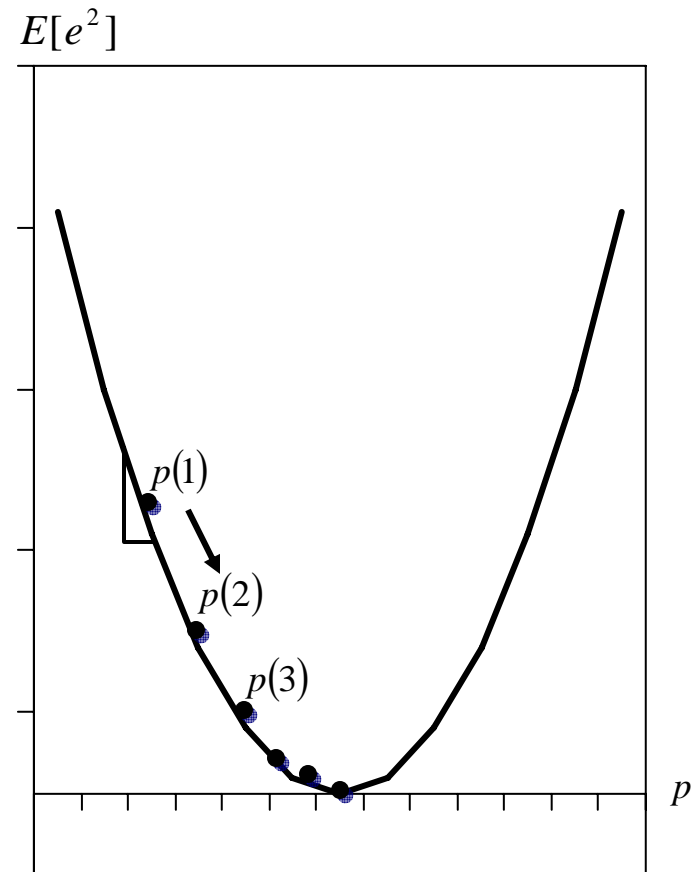


# LMS algorithm - Review

Single parameter case  
gradient descent  
adaptation:

$$\frac{\partial E[e^2]}{\partial p} < 0 \quad \therefore \Delta p > 0$$

$$\begin{aligned} \Rightarrow p(k+1) &= p(k) + \Delta p \\ &= p(k) - \mu \frac{\partial E[e^2(k)]}{\partial p} \end{aligned}$$



# LMS Algorithm - Review

■ How can we calculate  $\frac{\partial E[e^2]}{\partial p}$  ?

➤ Assume that  $E[e^2(k)] \approx e^2(k)$

$$\therefore \frac{\partial E[e^2]}{\partial p} \approx \frac{\partial(e^2)}{\partial p} = \frac{\partial(e^2)}{\partial e} \cdot \frac{\partial e}{\partial p} = 2e \cdot \frac{\partial(d-y)}{\partial p} = -2e \cdot \frac{\partial y}{\partial p} \equiv -2e \cdot u(k-i)$$

➤ Substitute this back into general gradient descent method:

$$p_i(k+1) = p_i(k) + 2\mu e(k)u(k-i)$$



# Jitter equalization

- Everything is the same, except  $e(k)$  is now sampled at zero crossings

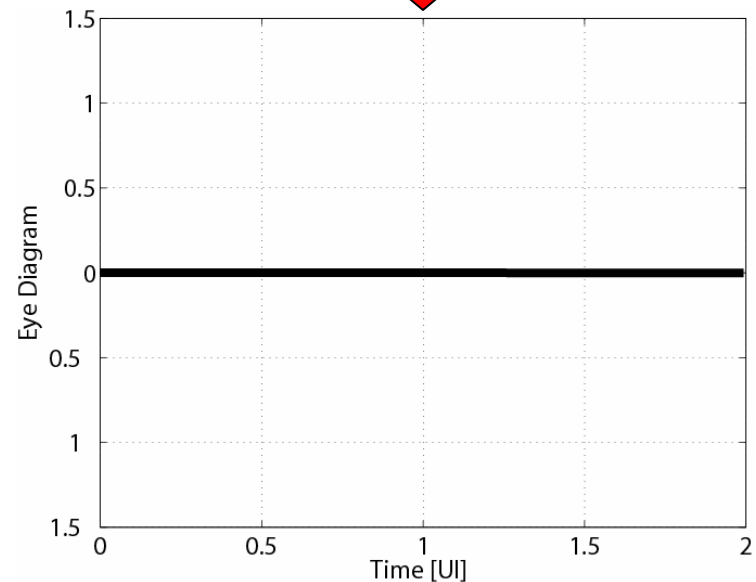
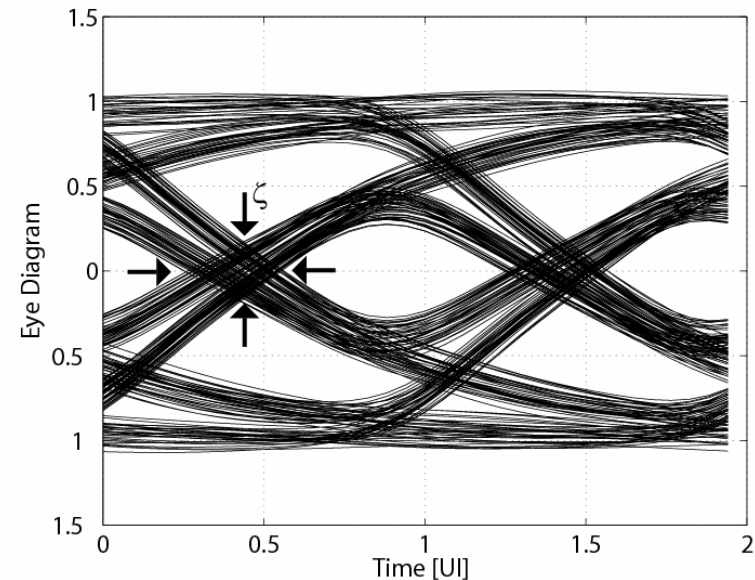
$$p_i(k+1) = p_i(k) + 2\mu e(k)u(k-i)$$

- **Note:**  $e(k)$  is often already sampled at zero crossings for timing recovery



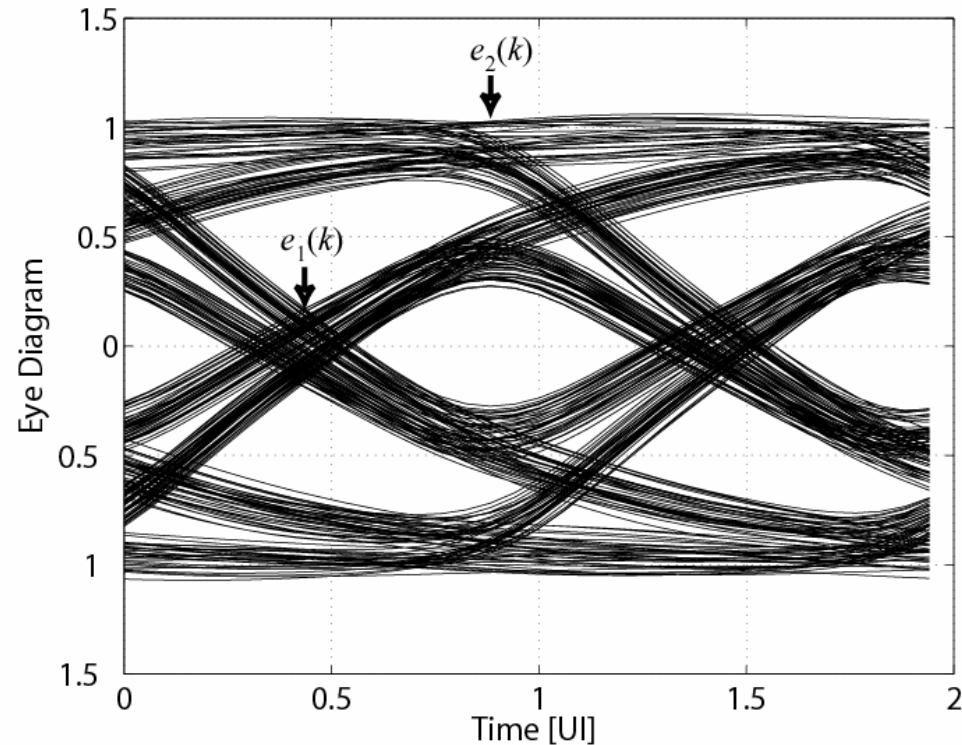
# Jitter equalization

- **Problem:**  $\zeta$  can be made zero by setting all  $p_i$ 's equal to zero
- Adaptation based on jitter criterion converges to this trivial operating point



# Jitter equalization

- **Solution:**  
Compromise  
between  
minimizing  $\xi$  and  
 $\zeta$  by alternating  
between (1) & (2)

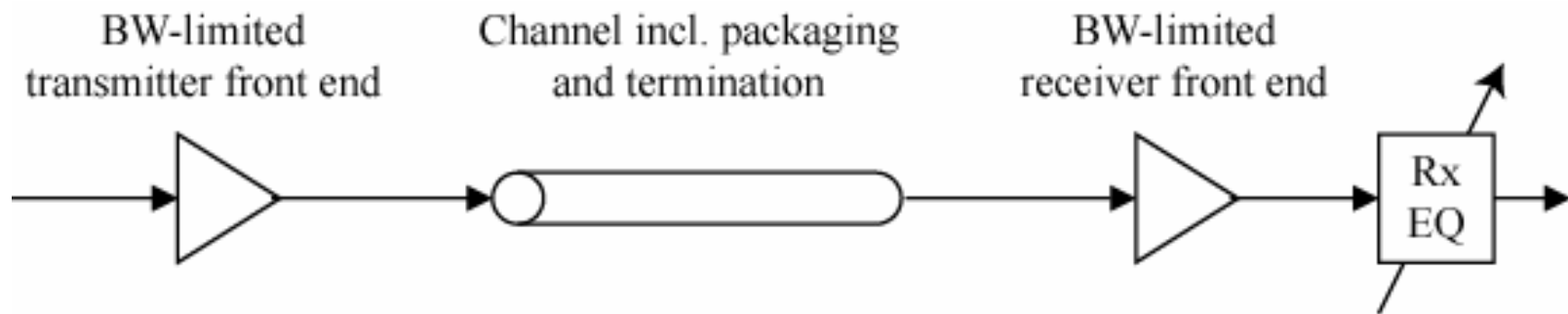


$$p_i(k+1) = p_i(k) + 2\mu_1 e_1(k) u(k-i) \quad (1)$$

$$p_i(k+1) = p_i(k) + 2\mu_2 e_2(k) u(k-i) \quad (2)$$

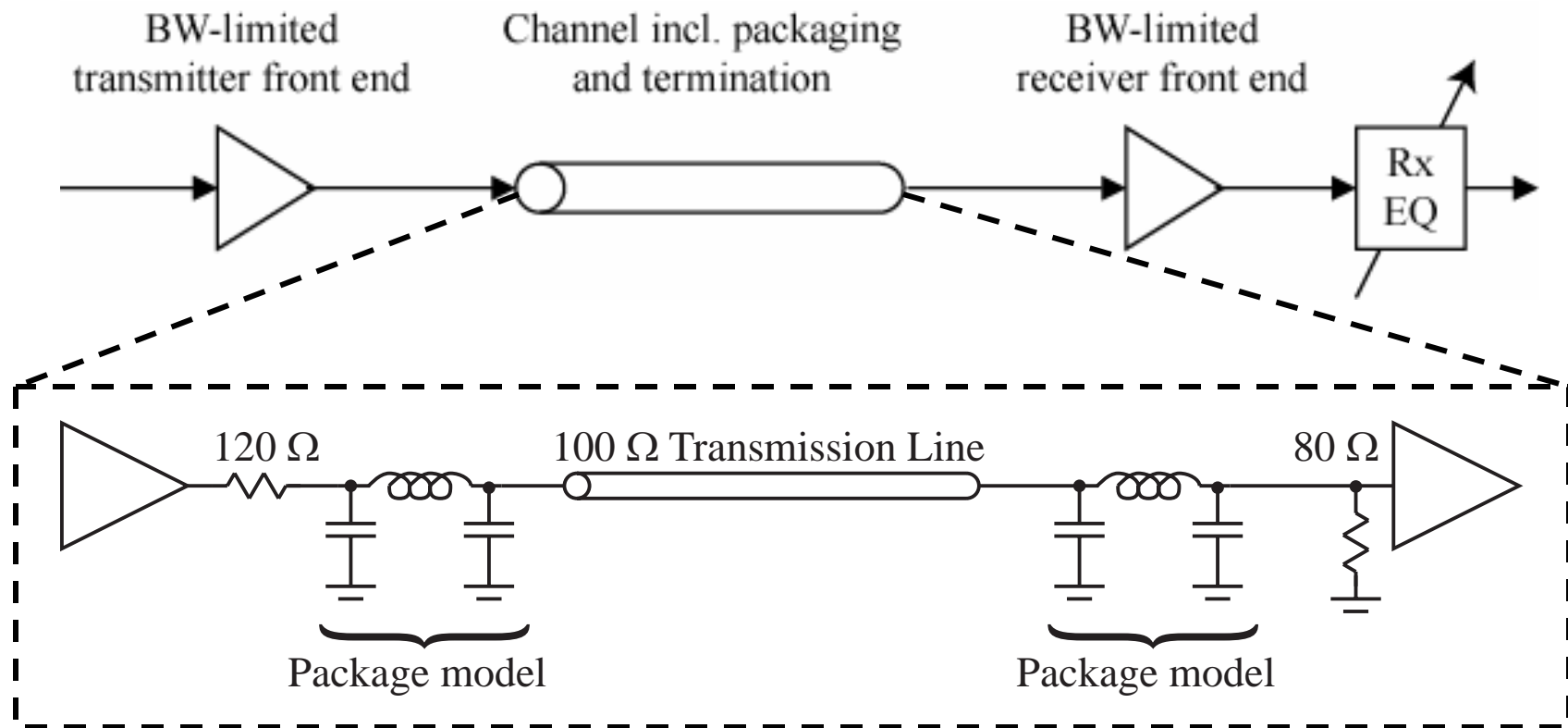
# Simulation Model

- System model used for simulations:



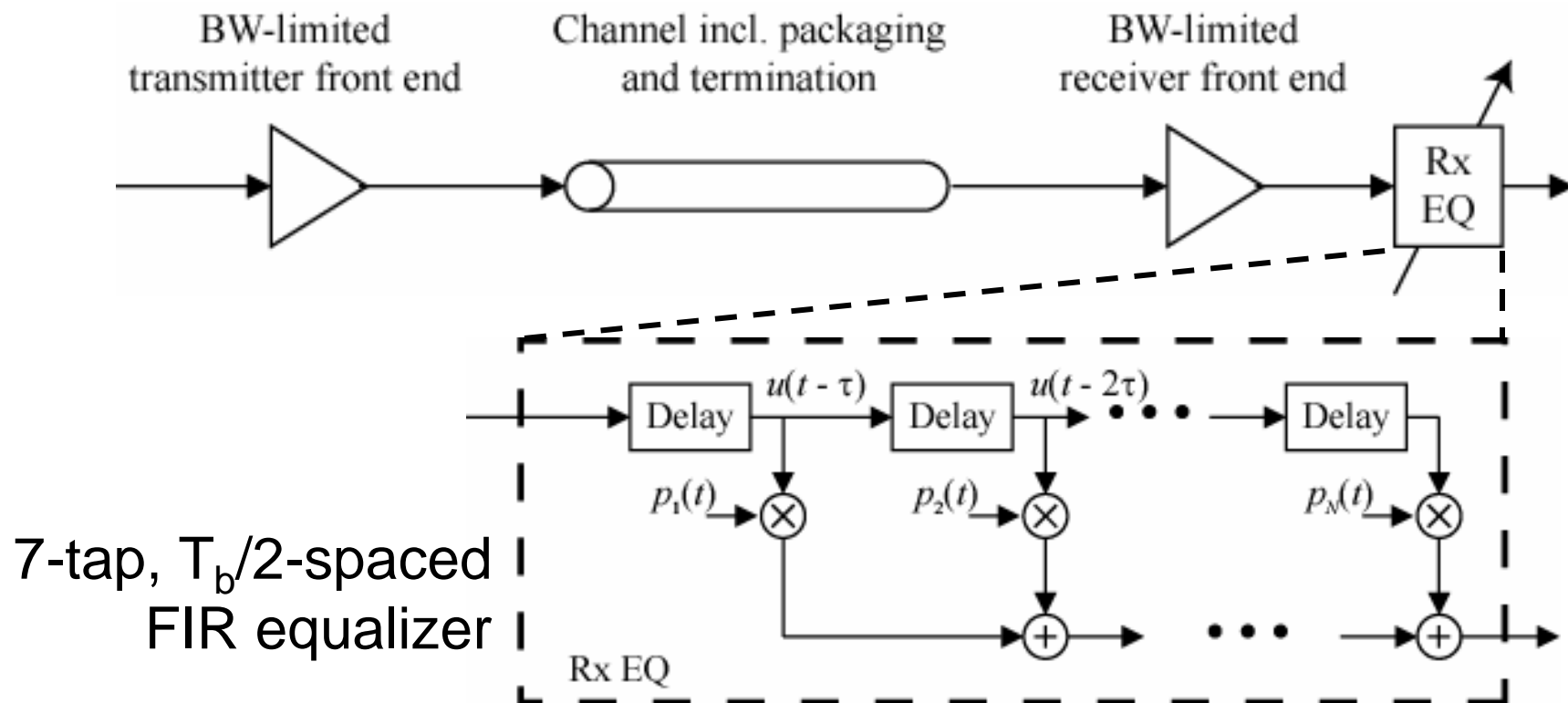
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- System model used for simulations:



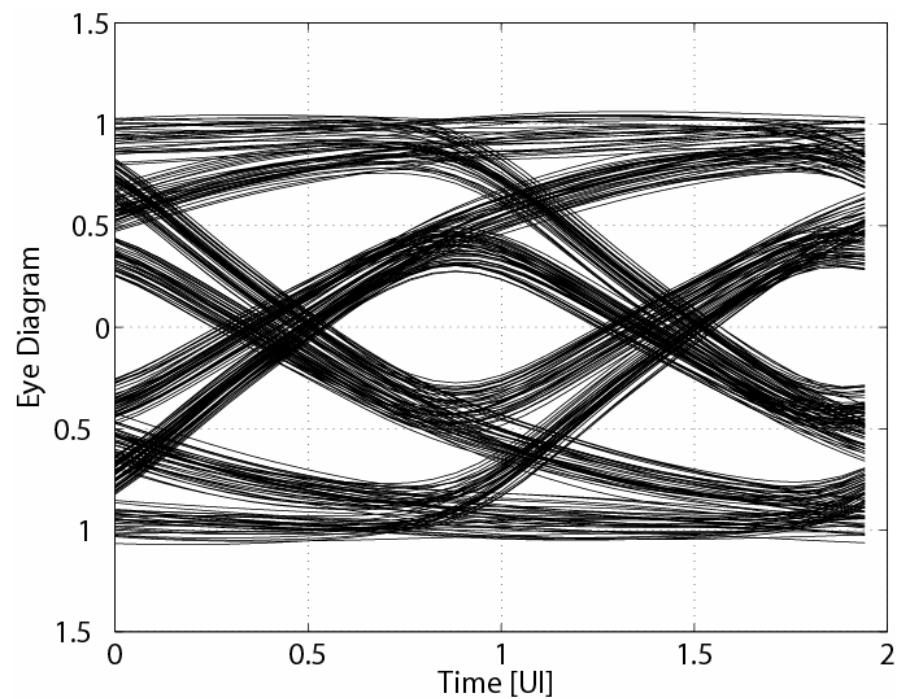
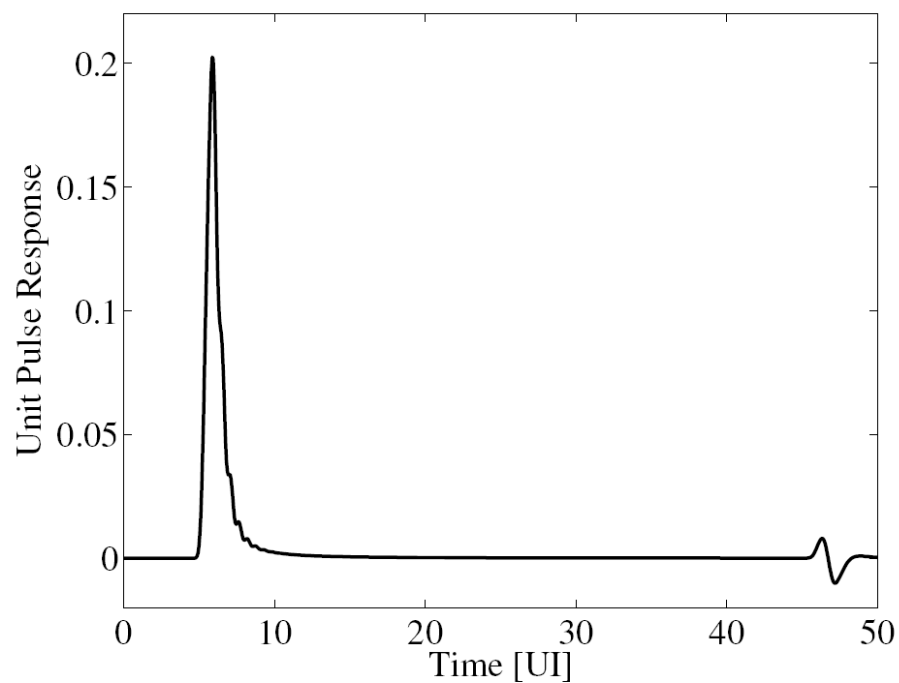
# Simulation Model

- System model used for simulations:



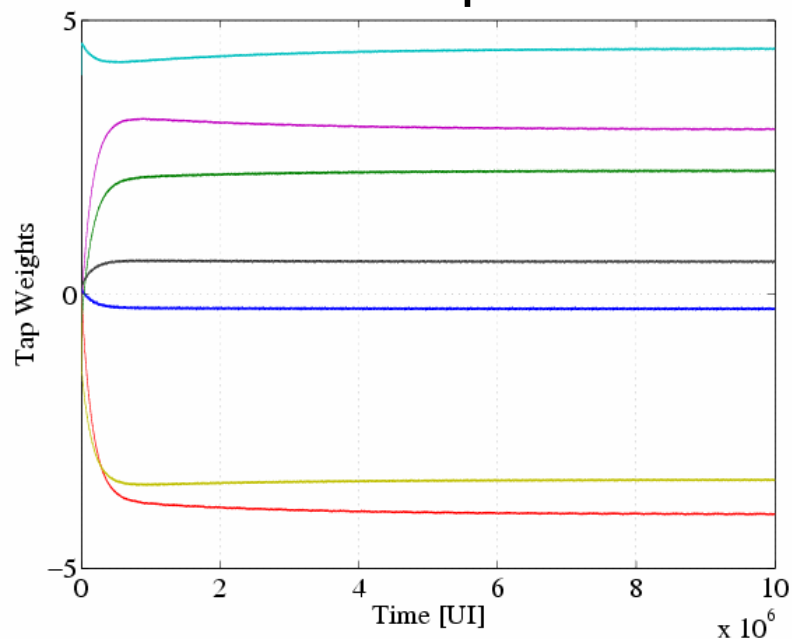
# Simulation Model

- Unequalized channel:

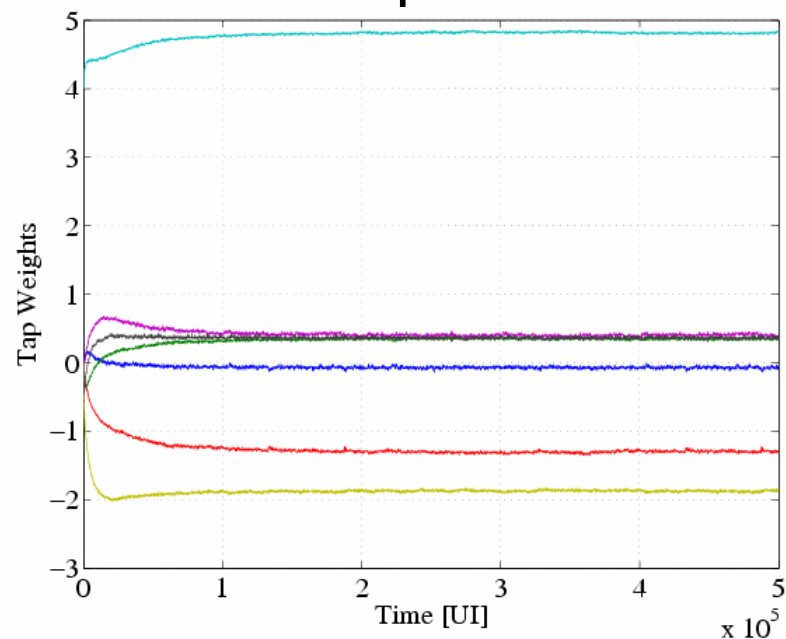


# Simulations

## LMS adaptation

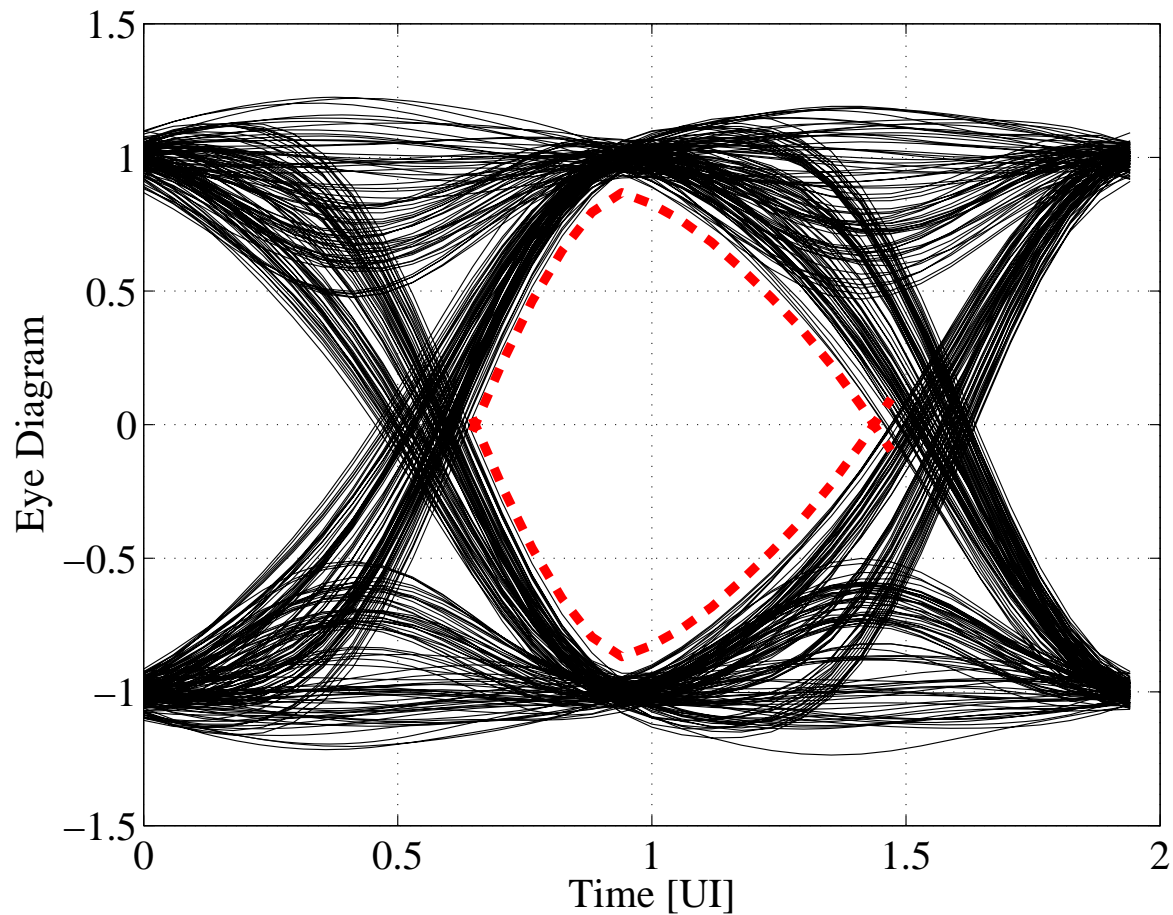


## Jitter equalization



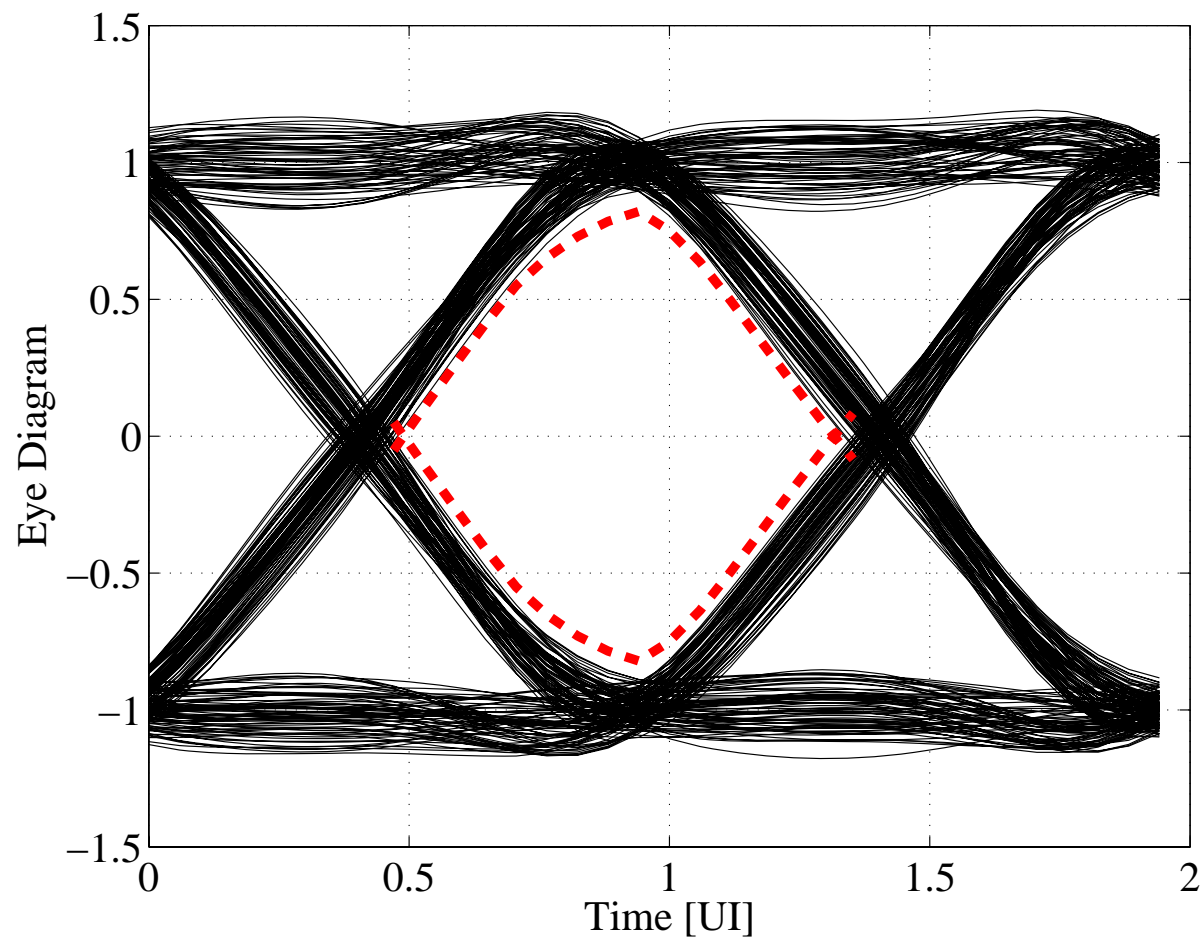
- Convergence of the tap weights over time is subject to the usual speed/accuracy tradeoffs

# Traditional LMS adaptation



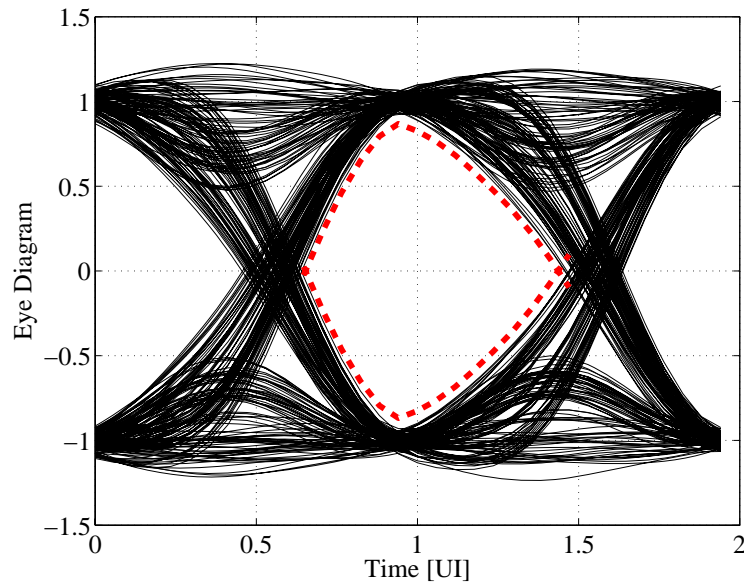


# Jitter equalization

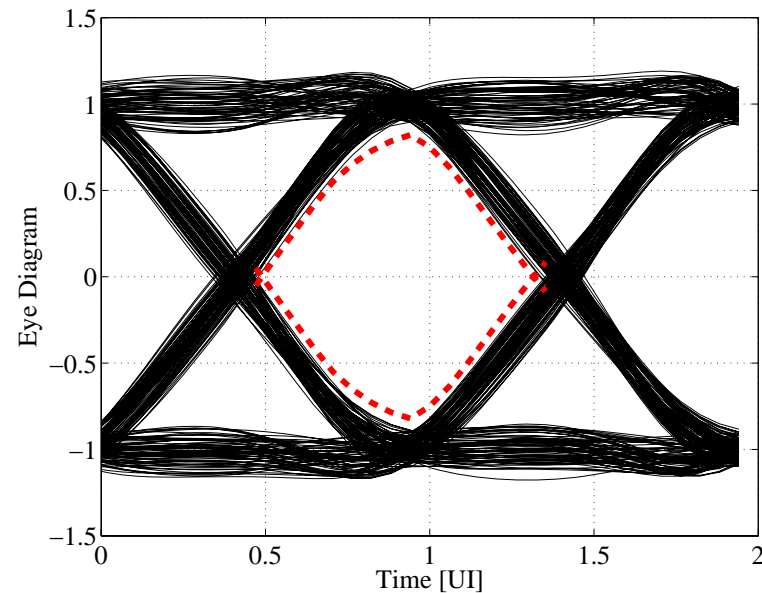


# Jitter equalization

LMS adaptation



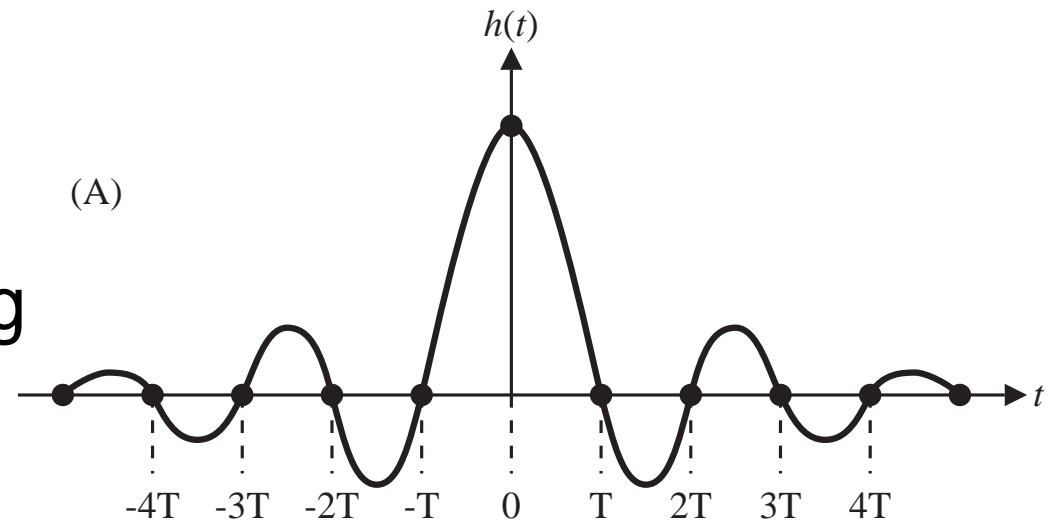
Jitter equalization



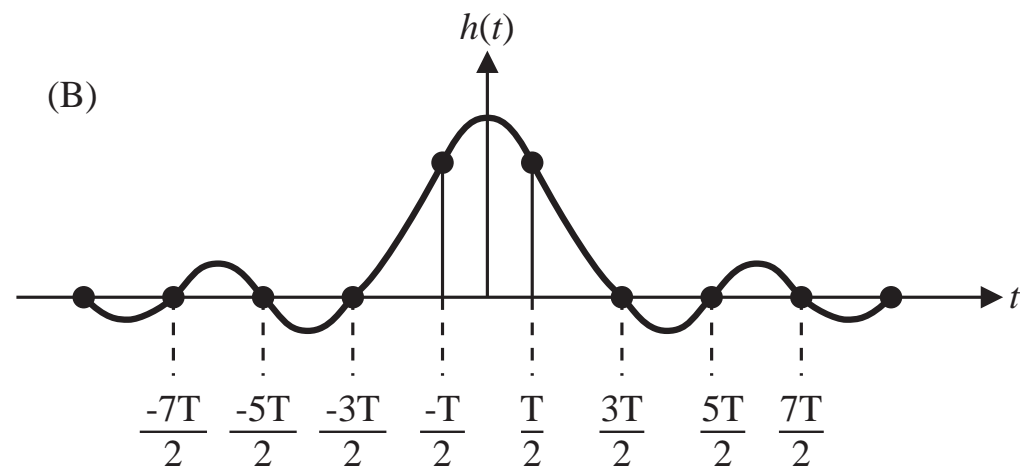
- In this case, jitter equalization provides 6% less vertical eye opening in exchange for 25% less pattern dependent jitter

# Nyquist criteria

- Nyquist 1 criterion:  
Zero ISI at sampling time

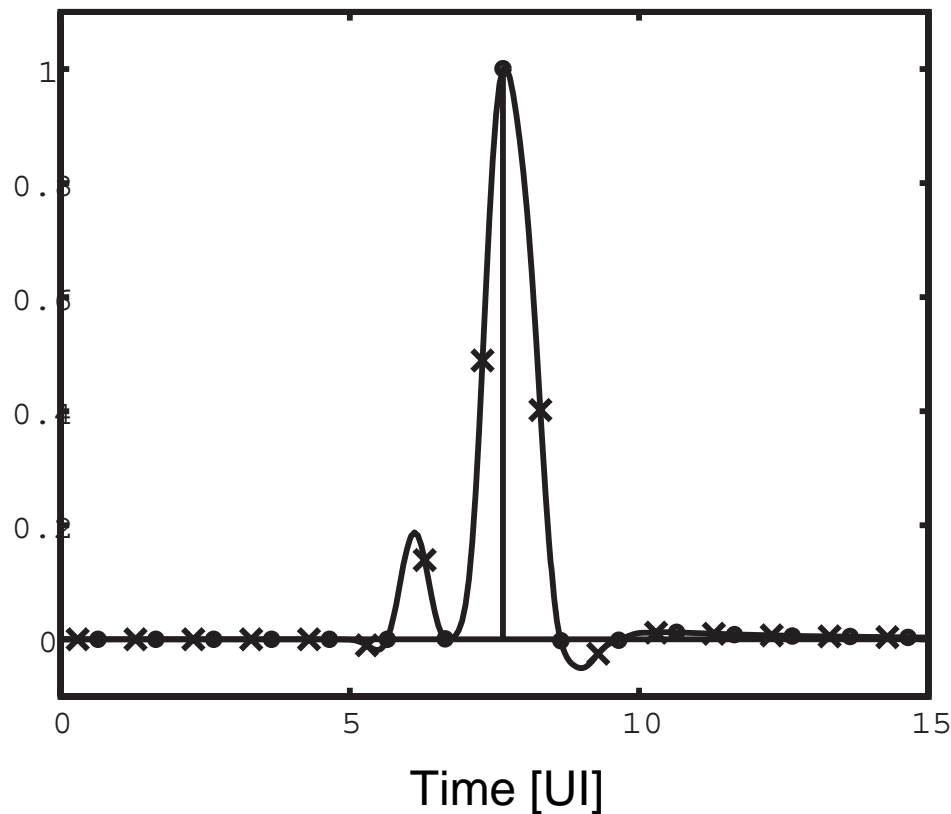


- Nyquist 2 criterion:  
Zero ISI at zero crossings



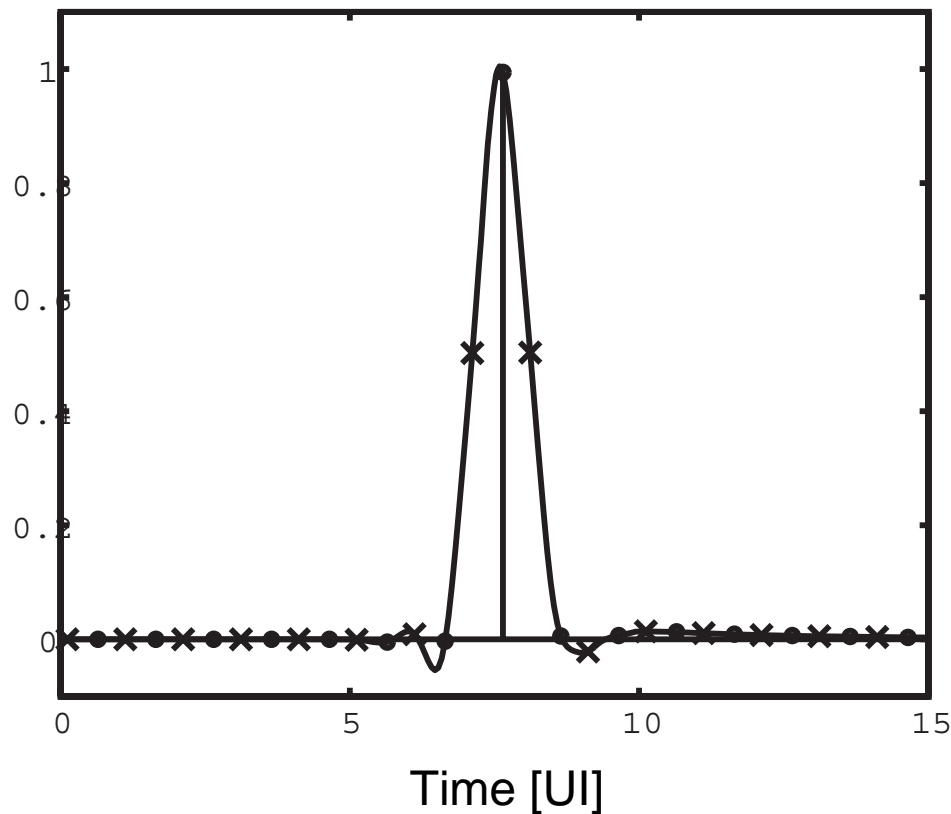
# Nyquist criteria

- Equalized response using LMS adaptation resembles Nyquist 1 pulse



# Nyquist criteria

- Using jitter equalization, the response resembles both Nyquist 1 & 2 pulses





# Conclusions

- The traditional LMS algorithm does not minimize jitter, even with a fractionally-spaced equalizer
- Often preferable to update equalizer parameters to minimize MSE alternately at the centre of the eye and at zero-crossings
- The resulting pulse response approximates both the Nyquist 1 & 2 criteria simultaneously
- The additional error information required may already be available in the timing recovery circuit