

An Example VHDL Application for the TM-4

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Introduction

This document describes a simple application circuit written in VHDL for the TM-4, and explains how to create, compile and run it.

The circuit implements a 32-bit counter. A program running on a workstation will read the output of the counter over the network.

Getting the Source for the Circuit

The source for this example circuit is on the EEGC machines in the directory `~tm4/examples/countervhd`.

Sign on to one of the EEGC Debian Linux workstations (ex: `crunch.eecg`). Make a new directory, and copy some of the files from the example directory:

```
mkdir counter
cd counter
set mydir=$cwd
pushd ~tm4/examples/countervhd
cp makefile counter.vhd counter.qsf counter.ports suncounter.c $mydir
popd
```

Add the following directory to your path, so that the Transmogriifier commands are available to you:

```
set path=(~tm4/bin $path)
```

You should probably add that line to your `.cshrc` file so that the change will be permanent.

The four files that you copied are:

<code>counter.vhd</code>	the circuit that will run on the Transmogriifier, described in VHDL
<code>counter.qsf</code>	a file containing commands for Altera's Quartus software
<code>counter.ports</code>	a description of the inputs and outputs of the circuit
<code>makefile</code>	used to compile the circuit and the program

`suncounter.c` a C program that runs on a UNIX workstation and talks to the circuit

Compiling the Example

To compile the circuit into a form that can be used to program the TM-4, type:

```
make bits
```

The `counter.vhd` source will be compiled by the VHDL compiler, and the resulting circuit description will be passed through a series of scripts and programs that will produce the programming bits for the chips on the board. It will place the results, along with a number of intermediate files, into a new subdirectory called `tm4` in your current directory. Any existing `tm4` subdirectory will be removed. The whole process will take about 3 minutes (on a 1.4 GHz Linux workstation).

To compile the program that runs on a Linux workstation and talks to the circuit, type:

```
make my_linux_counter
```

Downloading the Example to the Transmogriifier

First, you must decide which of the Transmogriifiers you want to use. By default, the commands will use the TM-4 attached to `crunch.eecg`. If you want any of the other Transmogriifiers, you must set the `TM4_SERVER` environment variable to the name of the workstation that is attached to the Transmogriifier you want, something like this:

```
setenv TM4_SERVER some_other_machine.eecg
```

At this point, you may want to run the Transmogriifier status monitor display on your workstation. Make sure your `DISPLAY` environment variable is set correctly and run:

```
tm4status -t &
```

This will produce a new window on your screen which displays the name of the design currently running in the machine, and a column of green and red lights.

Now use the `tm4get` command to reserve the Transmogriifier for 10 minutes:

```
tm4get
```

If someone else is using the machine, you will get a message telling you how long you will have to wait:

```
sorry, drg has it (priority 100) for 597 more seconds
```

To download your circuit into the TM-4, type:

```
tm4run
```

If you are running `tm4status`, you will see the lights go red as the previous design is stopped, and then

change to green as your design is loaded. The name of the directory containing your design will be displayed at the top of the status display.

Interacting with the Circuit

To communicate with the circuit, run the `my_linux_counter` program that you compiled earlier:

```
% my_linux_counter
0 1 2 3 4 5 6 7 8 9
```

Every time you run it, you will get another 10 numbers from the counter.

Stopping the Circuit and Releasing the Transmogriifier

You can stop the design, disabling the chips in the machine, by typing:

```
tm4 stop
```

You should now release the Transmogriifier so that someone else can use it:

```
tm4release
```

How the Sample Design Works

The circuit is written in VHDL. The complete `counter.vhd` file contains this:

```
library ieee;
use ieee.std_logic_1164.all;
use ieee.std_logic_arith.all;
use ieee.std_logic_unsigned.all;

entity counter is port(
    tm4_devbus : inout std_logic_vector(40 downto 0);
    tm4_glbclk0 : in std_logic
);
end;

architecture arch_counter of counter is

    type count_states is (count_null, count_idle, count_count);
    signal counter : std_logic_vector(31 downto 0);
    signal count : std_logic;
    signal count_state, next_count_state : count_states;
    signal count_reset : std_logic;
    signal want_count : std_logic;
    signal count_ready : std_logic;
    signal result : std_logic_vector(31 downto 0);

    component tm4_portmux
```

```
port(
tm4_devbus : inout std_logic_vector(40 downto 0);
result : in std_logic_vector(31 downto 0);
count_ready : in std_logic;
want_count : out std_logic;
tm4_glbclk0 : in std_logic);
end component;

begin

tm4_portmux_inst: tm4_portmux port map (
    tm4_devbus,
    result,
    count_ready,
    want_count,
    tm4_glbclk0);

process(count_state, want_count) begin
    case(count_state) is
        when count_null =>
            count_reset <= '1';
            next_count_state <= count_idle;
            count_ready <= '0';
            count <= '0';
        when count_idle =>
            count_reset <= '0';
            count_ready <= '1';
            count <= '0';
            if want_count = '1' then
                next_count_state <= count_count;
            else
                next_count_state <= count_idle;
            end if;
        when count_count =>
            count_ready <= '0';
            count_reset <= '0';
            if want_count = '1' then
                next_count_state <= count_count;
                count <= '0';
            else
                next_count_state <= count_idle;
                count <= '1';
            end if;
        end case;
    end process;

process(count_reset,tm4_glbclk0) begin
```

```
    if count_reset = '1' then
        counter <= "00000000000000000000000000000000";
        count_state <= count_idle;
    elsif tm4_glbclk0'event and tm4_glbclk0 = '1' then
        if count = '1' then
            counter <= counter + 1;
        end if;
        count_state <= next_count_state;
    end if;
    result <= counter;
end process;

end arch_counter;
```

The circuit has one 32-bit output port called `result`, and two 1-bit handshaking variables called `want_count` and `count_ready`. The circuit sits in an infinite loop, waiting for someone to ask for a count. It performs a handshake with the outside world using the `want_count` and `count_ready` variables, increments the counter, and waits for the next request.

The circuit uses the TM-4 ports package to communicate with the outside world. The connections to the outside world are handled by the component named `tm4_portmux_inst`. This component is automatically supplied by the TM-4 ports package. Read *The TM-4 Ports Package* for a description of how this works. The `counter.ports` file contains:

# Name	direction	bits	Handshake_from_circuit	Handshake_from_workstation
result	o	32	count_ready	want_count

It describes the single 32-bit output called `result` along with the two handshaking variables.

The `suncounter.c` program that runs on the workstation looks like this:

```
/* A program to test a simple counter on the TM-4, using the ports package */

#include <stdio.h>

main(argc, argv)
    int argc;
    char *argv[];
    {
    int portresult;
    int result[512 * 1024];
    int i, count;

    tm_init("");

    if((portresult = tm_open("result", "r")) < 0) {
        printf("Can't open port result\n");
        exit(1);
    }
}
```

```
    }  
  
    count = 10;  
    if(argc>1)  
        count = atoi(argv[1]);  
  
    if(tm_read(portresult, result, count * sizeof(int))  
        != (count * sizeof(int))) {  
        fprintf(stderr, "suncounter: error in reading\n");  
        exit(1);  
    }  
    for(i=0; i<count; i++)  
        printf("%d ", result[i]);  
    printf("\n\n");  
    exit(0);  
}
```

It initializes the ports package by calling `tm_init()`, opens the `result` port with `tm_open`, reads 10 values of the counter with a single call to `tm_read()` and then prints them out.